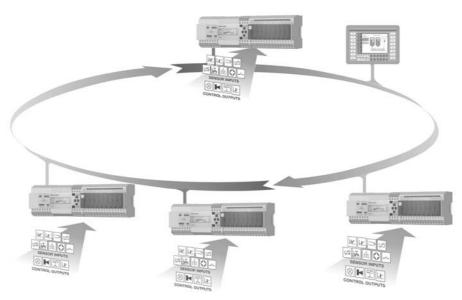




# COMMANDER TX2100 for MINING





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Further copies of this document are available from  $% \left\{ \left( 1\right) \right\} =\left\{ \left( 1\right) \right\} =\left\{$ 

trolex.com

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**Approvals and Certification** 

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PART 1

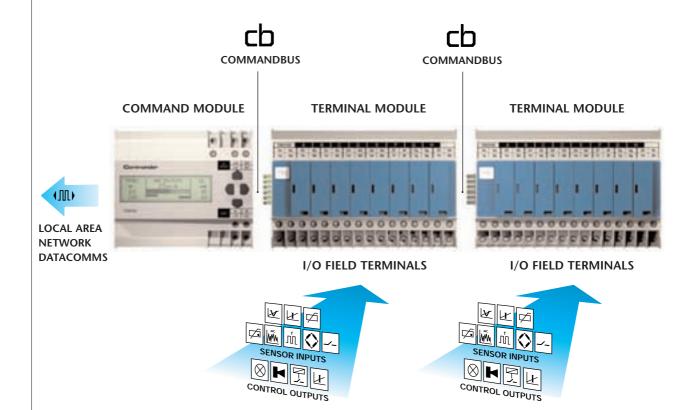
### commander

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PART 1
1. COMMANDER
PROFILE

## 1 commander profile



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### I/O COMMAND AND CONTROL SYSTEM FOR SENSORS, CONTROL DEVICES AND ALARMS

Modular Bus Configuration for simple compilation of local monitoring and control systems or large scale distributed Minewide monitoring installations.

- Bus expandable I/O up to a possible maximum of 960 addresses: analogue inputs, pulse/frequency inputs, switch inputs, output switching, analogue output control.
- User Configurable input signals and output drivers by simple channel card insertion.
- Programmable sensor response functions.
- Programmable monitoring and control functions.
- Data logging, up to 4000 readings for each I/O.
- Datacomms for distributed Minewide systems.
- Intrinsically safe for underground operation.



- Bus architecture for minimal cabling and wiring connections.
- Easy-to-use direct input programming through the navigator keypad.

Complete versatility of sensor and control device management with a vast range of operating options giving unparalleled simplicity of application.



PART 1
1. COMMANDER PROFILE

#### 1.1 AREA CLASSIFICATION

The complete Commander System is approved for use in Underground Hazardous Areas.

# GROUP I CATEGORY M1 HAZARDOUS AREAS ATEX DIRECTIVE 94/9/EC



- Certified Intrinsically Safe for use in Group I Hazardous Areas operating at 12V dc supply.
- Must be used with Group I approved sensors and/or control devices suitable for 12V dc.

**SERIES** 

.01





#### 1.2 **COMMANDER PROFILE**

#### **DESIGN INTEGRITY**

Operational safety to eliminate the possibility of incorrect plant output for a given input state is largely dependent upon correct software operation. Commander is designed within rigorous quality control techniques to ensure maximum reliability.

#### **CHECKING AND SYSTEM MONITORING.**

- All system communications links incorporate error checking and retry routines.
- All processor functions are 'watchdogged' against malfunction.
- Built-in self-test routines implement functional checks on all systems at system bootup, prior to permitting outputs to be changed under software control.
- All outputs are held in hardware-defined default states until all systems have been validated and will retain the 'last command' condition.
- Wherever practicable all input and output circuits are continuously monitored for short circuit and open circuit conditions. Output control relays have failsafe configuration. Fault conditions identified are individually alerted on the Command module and selective alarms can be initiated.

#### **INTRINSIC SAFETY**

Intrinsic safety is inherent in the electrical design of the system and will not be compromised by software malfunctions.

#### **SYSTEM INTEGRITY**

High levels of system security can be configured into a Commander system by adopting various design options.

- All I/O channel cards can be individually replaced without interrupting the normal function of the system.
- Additional I/O channel cards can be added without interrupting the normal function of the system.
- Input command signals can be 'voted' in any combination and I/O channels can be 'paralleled' for added security.
- Dual power supplies may be connected onto the Commandbus for standby failure protection where safety parameters permit.



caution Commander is a software-based system and relies on a single communications backbone and nonredundant processors. Safety critical installations where system multiple redundancy is required, must be combined with systems incorporating hard-wired safety circuits to provide redundancy capacity.



PART 1
1. COMMANDER
PROFILE

#### SAFETY INTEGRITY

- All modules and elements of the Commander system are individually coded to prevent incompatible or unsafe combinations. The coding system also ensures that only modules of the same area classification series (section 1.1) can be used together.
- All Commander modules and their combinations are manufactured in compliance with European EMC protection requirements for both radiated and received electromagnetic influence.







#### **DIAGNOSTICS**

Protected access is available to built-in menu based fault diagnostics. Various levels of software and function routines can be examined in detail for system analysis.

Access is also available to comms monitoring intelligence data.







Entry into these facilities is protected by an individual security keycode. This is available, together with user information, from the Trolex Commander application department.

#### **TECHNICAL SUPPORT AND TRAINING**

The Trolex team of system design engineers is available to assist
with Commander applications. Alternatively, we can design and
configure a complete functioning system including sensors,
software and final commissioning to specification.



#### **COMMANDER TRAINING**

One day training courses in Commander applications including a free Commander Configuration Software Package and hands-on practical system design examples.

**CONTACT** sales@trolex.com

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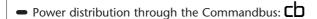
PART 1
2. TX2101
COMMAND
MODULE

# 2 TX2101 command module



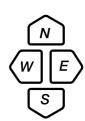
PART 1 2. TX2101 COMMAND MODULE The COMMAND MODULE is the hub of the Commander System. A powerful data processor with a graphical data display, data communications and navigator programming.

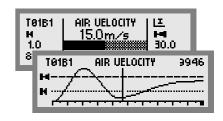
- Standard rail mounting modules to DIN 43 880 or panel mounting option.
- Commandbus communications to field I/O Terminal Modules up to a possible maximum of 960 I/O.

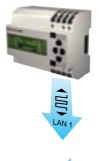


- Navigator keypad for convenient direct user programming of all functions:
  - Sensor input signal response characterisation.
  - Control output driver characteristics.
  - Data logging.
  - System diagnostics.
- Graphical LCD readout:
  - Sensor input signal display with selectable display format or trending.
  - Output driver status display.
  - Menu driven programming.
- LAN 1 datacomms port for local area networks, distributed Commander systems, external comms repeaters,
   PLC or PC user interface and data downloading.
   Screw terminals format for plant cable connections.
- LAN 2 datacomms port.
   Same as LAN 1 but outputted on a plug and socket connection for direct interface with data downloading devices.









LAN 2 ( III)



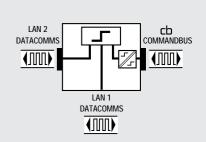


#### PART 1 2. TX2101 COMMAND **MODULE**

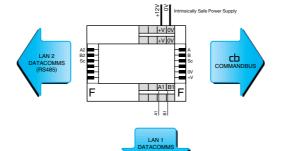
#### 2.1 **TX2101.01 COMMAND MODULE**



- System command and control centre.
- Expandable COMMANDBUS for I/O data up to 960 points of I/O.
- Same COMMANDBUS distributes the power.
- Programmable sensor response characteristics and output control functions.
- Integral LCD readout for I/O status and function programming.
- LAN 1 datacomms with screw terminal connections.
- LAN 2 datacomms with plug & socket connection.
- DIN rail mounting.



#### Connections:





The module must be mounted in a protective metal housing (eg: TX9202 or TX9204).



• The screen on the LAN 1/LAN 2 data cable is internally connected to the OV terminal and may be connected to a secure earth if required.

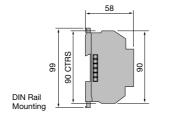


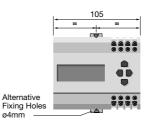
• The screen on the Commandbus is internally connected to the OV terminal. Connect OV to a secure earth at this point ONLY if required.

Supply Voltage:	12V dc from an external approved Group I Intrinsically Safe power supply (section 6). (Internally connected to the Commandbus for power distribution to other modules).
Current Consumption:	50mA.

	LAN 1 DATACOMMS	LAN 2 DATACOMMS	CP COMMANDBUS
Physical Layer:	RS485	RS485	RS485
Speed:	300115k Baud	300115k Baud	38400k Baud
Protocol	Modbus	Modbus	Trolex proprietary
Maximum Comms Points Maximum I/O	30 -	30 -	30 Terminal Modules 960 locations
Recommended Cable (with power) Recommended Cable (no power)	2 twisted pair • Individually Screened • Collectively Screened • B5308 pt1 1 twisted pair • Collectively Screened • B5308 pt1		
Max Cable Length: (Dependent upon cable type & baud rate)	1000m	1000m	1000m
Max Permitted Supply Current (+V & OV):	-	_	1.8 Amps

#### Dimensions:





All dimensions in mm.

Order Reference:

TX2101.01 COMMAND MODULE

GROUP I



**1** of 174 ISSUE F: 12/06



PART 1 2. TX2104 COMMAND MODULE

### 2.2 TX2104 COMMAND MODULE. PANEL MOUNTING OPTION

The TX2104 series of Command modules has the same function as the TX2101 Command module. It is suitable for flush mounting into panel and control desks for convenient integration into control layouts.



 Connect the TX2104 Command module directly to the COMMANDBUS using a COMMANDBUS cable (section 8).



■ The TX2104 Command module can also be connected to the COMMANDBUS through a TX2131 convertor module where screw terminal connections are preferred (section 5). This method is also useful when the Command module is located some distance away.





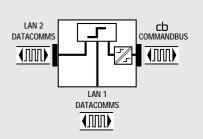


PART 1 2. TX2104 COMMAND **MODULE** 

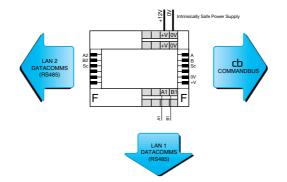
#### 2.3 **TX2104.01 COMMAND MODULE**



- System command and control centre.
- Expandable COMMANDBUS for I/O data up to 960 points of I/O.
- Same COMMANDBUS distributes the power.
- Programmable sensor response characteristics and output control functions.
- Integral LCD readout for I/O status and function programming.
- LAN 1/LAN 2 datacomms output.
- Panel mounting.



#### Connections:





The module must be mounted in a protective metal housing (eg: TX9202 or TX9204).



- Supplied with two six way connectors:
  - Commandbus connector.
  - LAN 2 datacomms connector.

See page 85 for corresponding 6 core connecting cable.



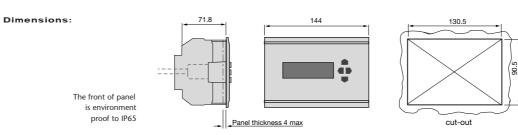
• The screen on the Commandbus is internally connected to the OV terminal. Connect OV to a secure earth at this point ONLY if required.



• The screen on the LAN 1/LAN 2 data cable is internally connected to the OV terminal and may be connected to a secure earth if required.

Supply Voltage:	12V dc from an external, approved Group I Intrinsically Safe power supply (section 6). (Internally connected to the COMMANDBUS for power distribution to other modules).
Current Consumption:	100mA.

	LAN 1 DATACOMMS	LAN 2 DATACOMMS	CD COMMANDBUS
Physical Layer:	RS485	RS485	RS485
Speed:	300115k Baud	300115k Baud	38400k Baud
Protocol	Modbus	Modbus	Trolex proprietary
Maximum Comms Points Maximum I/O	30 -	30 -	30 Terminal Modules 960 locations
Recommended Cable (with power) Recommended Cable (no power)			
Max Cable Length: (Dependent upon cable type & baud rate)	1000m	1000m	1000m
Max Permitted Supply Current (+V & OV):	_	_	1.8 Amps



All dimensions in mm.

Order Reference:

TX2104.01 COMMAND MODULE

GROUP I



**B** of 174



PART 1
3. TX2102
TERMINAL
MODULE

### 3 TX2102 terminal module



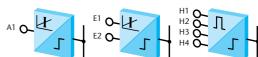


PART 1 3. TX2102 TERMINAL MODULE The TERMINAL MODULE accommodates up to 8 CHANNEL CARDS in any combination of I/O functions.



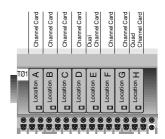
#### 3.1 CHANNEL CARD ADDRESS

 SINGLE, DUAL or QUAD function channel cards can be fitted in any position (section 4).



Each I/O function on a channel card is called a LOCATION.
 The ADDRESS of a location is determined by the position it takes up in the TERMINAL MODULE, eg:

Address	Terminal Module	Channel Card Location	Type
T 01 A1	01	A1	single
T 01 E1 T 01 E2	01	E1 E2	dual
T 01 H1 T 01 H2 T 01 H3 T 01 H4	01	H1 H2 H3 H4	quad



#### **ADDRESS ALLOCATION**

Each terminal module must be allocated with a unique address number - T01 up to T30. (A self adhesive label is provided for marking the appropriate terminal module reference).



- Remove the cover panel to reveal the setup switches and set a module reference number : 01 to 30.
- Numbers may be allocated in any order of distribution on the Commandbus.



A terminal module with a reference number set at 00 will be disregarded by the Commandbus - useful for maintenance purposes.

**1** of 174

PART 1 TX2101 COMMAND MODULE

### 3.2 TERMINAL MODULES couple directly to the COMMAND MODULE through the COMMANDBUS.

■ Up to 30\* TERMINAL MODULES can be combined on one Commandbus permitting a total maximum of 240 channel cards.

Any of the channel cards may be SINGLE, DUAL or QUAD location types (section 4). (Theoretical maximum locations: 240 x QUAD = 960). (\*Subject to certification limitations).





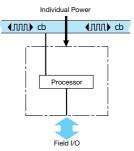


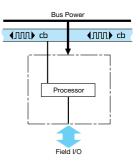
#### 3.3 SYSTEM POWER DISTRIBUTION

- Power is also distributed via the COMMANDBUS.
- The power source that provides power to the COMMAND MODULE will also power the TERMINAL MODULES of a close-coupled Commander system, through the Cb connector.
- The same power can also be supplied to *dispersed* TERMINAL MODULES through the Commandbus data cable, when the power connecting cores of the cable are utilised (section 8.1).
- If the power demand of a Commander system exceeds the current capability of a single power supply, additional power supplies can be added at selected TERMINAL MODULES or COMMANDER STATIONS (section 5.4).
- The internal power supply system within each TERMINAL MODULE also provides power at the appropriate voltage for energising sensors and field devices that are connected to the channel cards (section 3.10).









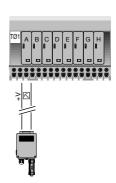
**1**6 of 174



PART 1
3. TX2102
TERMINAL
MODULE

### 3.4 CONNECTING SENSORS & PLANT DEVICES TO A TX2102 TERMINAL MODULE

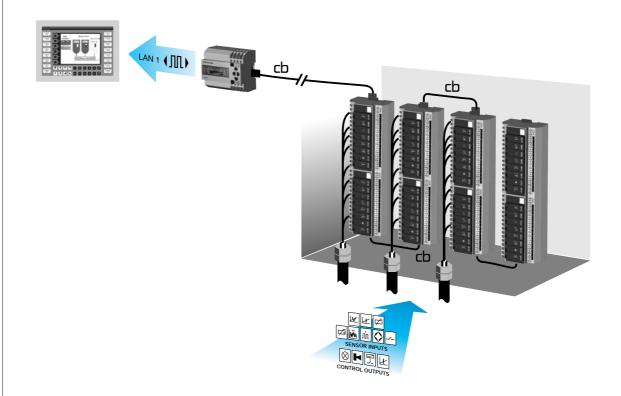
Incoming cable connections from remote sensors and plant control devices can be connected *directly* to the connecting terminals of each terminal module.



The heavy duty, clamp type terminals will easily accommodate cable conductors up to 2.5mm<sup>2</sup>, so the terminal modules can, in effect, be used as the incoming termination port of the system.

This completely eliminates the additional internal wiring that is normally necessary to interconnect with a conventional terminal rail.

Similarly, the individual *through* wiring is not needed from the terminal rail as the I/O data is now carried in a single COMMANDBUS cable to the control or display system employed.



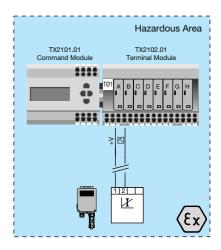


PART 1 TX2102 COMMAND MODULE

#### 3.5 GROUP I HAZARDOUS AREA SYSTEMS (SERIES 01)

Group I hazardous area Commander systems operate at 12V dc.

The complete system is powered from a single intrinsically safe
12V dc power source and all elements of the system, including an approved sensor, can be mounted in the hazardous area.



#### **3.6 FAILURE MODE**

The system is designed to ensure that data will continue to pass along the Commandbus, in the unlikely event that a Terminal Module processor should fail. The remainder of the Commandbus will be fully supported and a 'Fail' status report will appear at the Command Module.

If there is a total loss of data on the Commandbus, all outputs will retain the 'last command' condition and a 'loss of data' report will be given at the Command Module.



PART 1 TX2101 COMMAND MODULE

### 3.7 POWER DISTRIBUTION within the TERMINAL MODULE and CURRENT AUDITING.

■ All the power consumed by a Terminal Module is derived from the power rail of the Commandbus that runs through the Commandbus connectors situated at each end of the module (section 5.4).

The total aggregate power taken by an individual Terminal Module comprises three main elements:

1. Processor Current (PI): The nominal current required to drive the main processor of the Terminal

Module (section 3.8).

2. Channel Card Current (CI): The current required to drive the processor of each individual channel card.

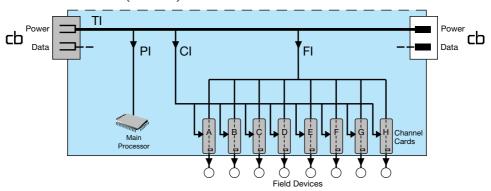
This is a variable value related to the quantity and types of channel card fitted

in the Terminal Module (section 4).

3. Field Device Current (FI): Auxiliary current is made available at each channel card to power up sensors

and field devices. On some channel cards the power for the field device (FI) is a pre-determined or insignificant value. On others the field device current (FI) is dependent upon the type of device connected and the method of connection

(section 4).



Terminal Module Current (TI) = PI

+ CIA + CIB + CIC + CID + CIE + CIF + CIG + CIH (as applicable)

+ FIA + FIB + FIC + FID + FIE + FIF + FIG + FIH (as applicable)



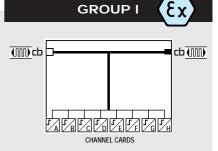


#### 3.8 TX2102.01 TERMINAL MODULE

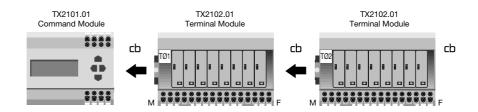


DATA

- Accommodates 8 single, dual or quad location channel cards.
- **■** Terminal modules couple together using integral Commandbus connectors.
- Power distribution on the same COMMANDBUS.
- Bus expandable up to 30 similar Terminal Modules on one Commandbus.
- DIN rail mounting.



#### Connections:

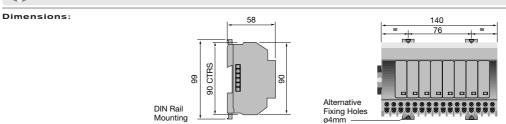


Individual terminal connections are appropriate to each channel (section 4).

Supply Voltage:	12V dc Intrinsically Safe direct from the Commandbus (section 6). (NOT isolated between Commandbus ports).
Processor Current (PI):	15mA (excluding channel cards).
Max Cable Length:	1000m (dependent upon installation parameters).
Limit:	30 Terminal Modules on one Commandbus.



• The total cumulative maximum current that may be delivered to a Commander system and sensors is limited to 1.8 amps from a single IS power supply (section 6.3.2).



All dimensions in mm.

Order Reference: TX2102.01 TERMINAL MODULE GROUP I (Ex)

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PART 1
4. TX2141
CHANNEL CARDS

# 4 TX2141 channel cards and accessories





The function of each I/O location is determined by the CHANNEL CARDS.

- **4.1 ANALOGUE INPUT CHANNEL CARDS.** for analogue sensing devices.
- 0-1-1
- **4.2 PULSE FREQUENCY INPUT CHANNEL CARDS.**Pulse processing and counting.



**4.3 ONOFF/STATE INPUT CHANNEL CARDS.**Switches, NAMUR sensors, fire and alarm systems.



**4.4 ONOFF/STATE OUTPUT CHANNEL CARDS** for plant control devices, alarms and interfacing signals.



**4.5 ANALOGUE OUTPUT CHANNEL CARDS.**Motorised valves, servos and controllers.

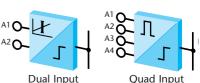


#### **CHANNEL FORMAT**

 Each TX2102 TERMINAL MODULE has accommodation for up to 8 CHANNEL CARDS which can be assembled in any combination.
 The cards are plug-in and can be changed at any time without interrupting the system. Insert a small screwdriver to release the latch when removing a channel card.



 Many CHANNEL CARDS are dual or quad function so up to 32 function LOCATIONS can be operated in a TERMINAL MODULE.



 An LED on the front of each channel card flashes RED when command instructions are being executed. The LED will remain either permanently ON or permanently OFF if a channel FAULT occurs.



■ The ADDRESS of a location is determined by the position it takes up in the TERMINAL MODULE and into which terminal module it is fitted (section 3).





Page

PART 1 4. TX2141 CHANNEL CARDS

#### 4.1 ANALOGUE INPUT CHANNEL CARDS.

4.1.1	TX2141.301	420mA input	0-FT	24
4.1.2	TX2141.302	Dual 420mA input	0月	25
4.1.3	TX2141.303	0.42V input	0 K	26
4.1.4	TX2141.304	Dual 0.42V input	0-1-1	27
4.1.6	TX2141.306	PT100 Temperature device input	o-\2	28
4.1.7	TX2141.307	Dual PT100 Temperature device input	0-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	29
4.1.8	TX2141.308	Dual Semi-conductor temperature device input	o 1 1 o 位	30
4.1.9	TX2141.309	ac input	0-2-1	31
4.1.10	TX2141.310	mV input	o my	32





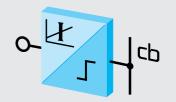
PART 1 4. TX2141 CHANNEL CARDS

#### TX2141.301 CHANNEL CARD 4.1.1

- 2, 3 or 4 wire current regulated process input signals.
- Power supply output available for sensor.
- Configurable to other current sensing ranges i.e. 0...20mA, 0...10mA, etc. to specification.

#### **ANALOGUE INPUT**

4...20mA signal



Connections:	2 wire	3 wire	4 wire
(Channel A)	A1  2a 4a  1a 3a  A 2	A1  2a 4a  1a 3a  A > > > > > > > > > > > > > > > > > >	A1  2a 4a  1a 3a  A A A A A A A A A A A A A A A A A A A
	• 2 wire signal loop • Line powered sensor	2 wire signal loop     Additional wire for sensor power 0V	<ul><li> 2 wire signal loop</li><li> 2 wires for power +V, 0V</li></ul>
Field Device Current (FI):	20mA for the signal loop.	20mA for the signal loop + addition	onal current to power the sensor.

	TX2141.301.01
Sensor Voltage:	12V dc
Channel Card Current (CI):	15mA
Maximum Cable Length:	
1mm²	2000m
2.5 mm <sup>2</sup>	5000m
Max External Loop Resistance:	600 ohms
Recommended Cable:	2, 3 or 4 core.
Maximum Cable L/R:	100μH/ohm (P)

T X 2 1 4 1 . 3 0 1 . 0 1 CHANNEL CARD GROUP I  $\langle \xi_{x} \rangle$ Order Reference:

Please specify: • Specific current measuring range.

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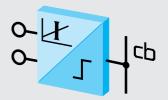
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.2 TX2141.302 CHANNEL CARD

- Two independent inputs.
- 2 wire current regulated process input signals.
- Line powered sensors.
- Configurable to other current sensing ranges i.e. 0...20mA, 0...10mA, etc. to specification.



4...20mA signals



Connections:	
(Channel A)	A1 A2  2a 4a  1a 3a  2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
Field Device Current (FI):	20mA for each connected sensor.

	TX2141.302.01
Sensor Voltage:	12V dc
Channel Card Current (CI):	15mA
Maximum Cable Length:	
1mm²	2000m
2.5 mm <sup>2</sup>	5000m
Max External Loop Resistance:	600 ohms
Recommended Cable:	2, 3 or 4 core.
Maximum Cable L/R:	100μH/ohm (P)

Order Reference: T X 2 1 4 1 . 3 0 2 . 0 1 CHANNEL CARD GROUP I  $\langle E_{X} \rangle$ 

Please specify: • Specific current measuring ranges (For A1 and A2 locations).

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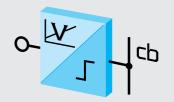
PART 1 4. TX2141 CHANNEL CARDS

#### TX2141.303 CHANNEL CARD 4.1.3

- 2, 3 or 4 wire voltage signals.
- Power supply output available for sensor.
- Configurable to other voltage sensing ranges i.e. 0...5V, 0...2V, 0...1V, etc.

#### **ANALOGUE INPUT**

0.4...2 Volt signal



Connections:	2 wire	3 wire	4 wire
(Channel A)	A1  2a 4a  1a 3a  A 5  PSU  • 2 wire voltage signal • Sensor fed by independent	A1  2a 4a  1a 3a  1a 3	A1  2a 4a  1a 3a  A2  A3  A4  1a 3a  A4  A4  A4  A4  A4  A4  A4  A4  A4  A
Maximum Cable Length:	or integral power supply	10mA Sensor 40mA Sensor	10mA Sensor 40mA Sensor
1mm <sup>2</sup>	- 4000m	80m 20m	2000m 2000m
2.5mm²	10000m	200m 50m	
		Volt drop introduced on to the common 0V line by the supply feed to the sensor will be superimposed on to the signal. The signal accuracy shift caused by this is the factor that limits the cable length.	The potential cable length is limited by the permissible volt drop in the +V and 0V power supply feed conductors to the sensor that will ensure an adequate operating voltage supply at the sensor.
Field Device Current (FI):	Insignificant.	Current required to power the sensor.	

TX2141.303.01	
12V dc	
15mA	
100mA	
>10k ohms	
2, 3 or 4 core	
100μH/ohm (P)	

T X 2 1 4 1 . 3 0 3 . 0 1 CHANNEL CARD GROUP I  $\langle E_x \rangle$ Order Reference:

Please specify: • Specific voltage measuring range.

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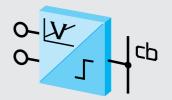
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.4 TX2141.304 CHANNEL CARD

- Two independent inputs.
- Power supply output available for sensors.

#### **DUAL ANALOGUE INPUT**

0.4...2 Volt signals



Connections:	2 wire	3 wire	
(Channel A)	A1 A2  2a 4a  1a 3a    W   W    • Dual 2 wire voltage signals • Sensors have independent or integral power supply	A1 A2  2a 4a  1a 3a  W W W  • Dual 2 wire voltage signals • +V power supply to sensors • 0V power supply to sensors combined with \( \sum 0V \)	
Maximum Cable Length:	4000m	10mA Sensor         40mA Sensor           80m         20m	
2.5mm²	10000m	200m 50m	
		Volt drop introduced on to the common 0V line by the supply feed to the sensor will be superimposed on to the signal.  The signal accuracy shift caused by this is the factor that limits the cable length.	
Field Device Current (FI):	Insignificant.	Current required to power the sensor.	

	TX2141.304.01	
Sensor Voltage:	12V dc	
Channel Card Current (CI):	15mA	
Max. Sensor Supply Current:	100mA	
Input Impedance:	>10k ohms	
Recommended Cable:	2, 3 or 4 core	
Maximum Cable L/R:	100μH/ohm. (P)	

Order Reference: TX2141.304.01 CHANNEL CARD GROUP I (Ex)

Please specify: • Specific voltage measuring ranges (For A1 and A2 locations).

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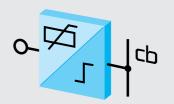
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.6 TX2141.306 CHANNEL CARD

- Standardised to DIN 43760, BS 1904 and IEC 751.
- Ranges: Selectable scaling from -50°C. up to 400°C.
- Optional 4 wire or 2 wire connection.



PT100 temperature signal



Connections:	4 wire	2 wire
(Channel A)	A1  2a 4a  1a 3a	A1  2a 4a  1a 3a
Maximum Cable Length:		
1mm²	100m	10m
2.5mm <sup>2</sup>	100m	25m
Field Device Current (FI):	1n	nA

	TX2141.306.01	
Channel Card Current (CI):	15mA	
Recommended Cable:	2 core • overall screen or 4 core • overall screen	
Maximum Cable L/R:	100μH/ohm (P)	

Order Reference: TX2141.306.01 CHANNEL CARD GROUP I  $\langle \xi_X \rangle$ 

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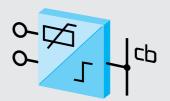
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.7 TX2141.307 CHANNEL CARD

- Two independent inputs.
- Standardised to DIN 43760 and BS 1904.
- Ranges: Selectable scaling from –50°C. up to 400°C.



PT100 temperature signals



Connections:	
(Channel A)	A1 A2  2a 4a  1a 3a
Field Device Current (FI):	1mA per location

	TX2141.307.01	
Channel Card Current (CI):	15mA	
Maximum Cable Length:		
1mm²	10m	
2.5mm <sup>2</sup>	25m	
Recommended Cable:	2 core • overall screen per input	
Maximum Cable L/R:	100µH/ohm (P)	

Order Reference: T X 2 1 4 1 . 3 0 7 . 0 1 CHANNEL CARD GROUP I  $\langle \xi_{x} \rangle$ 

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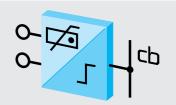
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.8 TX2141.308 CHANNEL CARD

- Two independent inputs.
- Linearised input.
- Selectable scaling from -50°C up to 200°C.
   (KTY21: -50°C...100°C) (KTY84: -50°C...200°C)



semiconductor temperature signals



Connections:	
(Channel A)	A1 A2  2a 4a  1a 3a  ——————————————————————————————————
Field Device Current (FI):	1mA per location

	TX2141.308.01	
Channel Card Current (CI):	15mA	
Maximum Cable Length:	200m	
Recommended Cable:	2 core	
Maximum Cable L/R:	100μH/ohm ®	

Order Reference: TX2141.308.01 CHANNEL CARD GROUP I (Ex)

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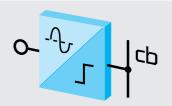
#### PART 1 4. TX2141 HANNEL CARDS

#### 4.1.9 TX2141.309 CHANNEL CARD

- ac voltage signals from Vibration Sensors, load cells, ac generators, power measuring instruments.
- ac RMS detection.
- Bandpass frequency response (3dB): 10Hz...100Hz (Velocity). 500Hz...10kHz (Acceleration).
- ICP and dc powered sensors.
- **■** For use with Trolex TX5630 Series Vibration Sensors.

#### **ANALOGUE INPUT**

ac voltage signals



Connections:		
(Channel A)	A1 2a 4a	A1 2a 4a
	1a 3a	1a 3a
	ICP Sensor (TX5630)	dc Powered Sensor
Field Device Current (FI):	Insign	ificant.

	TX2141.309.01		
Channel Card Current:	30mA		
Maximum Cable Length:	200m		
Recommended Cable:	ICP Sensor: 2 core • overall scree	en	
	dc Powered Sensor: 3 core • overall scree	en	
Maximum Cable L/R:	100μH/ohm	P	



T X 2 1 4 1 . 3 0 9 . 0 1 CHANNEL CARD Order Reference:

GROUP I  $\langle \mathcal{E}_{x} \rangle$ 

- Bandpass frequency 10Hz...100Hz (Velocity)
- Bandpass frequency 500Hz...10kHz (Acceleration)
- Specific input filter range.
- Sensor sensitivity (mV/g).

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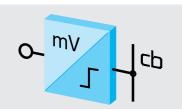
PART 1 4. TX2141 CHANNEL CARDS

#### 4.1.10 TX2141.310 CHANNEL CARD

- Low level inputs from balanced bridges, load cells, strain gauges, pressure sensors and gas sensors.
- Measuring range options.
- Current regulated sensor energising supply output.
- Zero offset and span calibration.
- Accepts input signals from TX6250 series Infra-Red Temperature Sensors.
   Application specific ranges from -20°C up to 400°C.



mV signals



Balanced TX6250 series Bridge Infra Red Temperature Sensor	Connections: (Channel A)	A1
Field Device Current (FI): Current required to power the sensor.		Balanced TX6250 series Bridge Infra Red Temperature Sensor

_		
	TX2141.310.01	
Channel Card Current (CI):	15mA	
Measuring Ranges:	02mV / 05mV / 010mV / 050mV / 0100mV / 01000mV / 02000mV	
Sensor Current Regulation:	050mA	
Input Impedance:	100k ohms (P)	
Max Sensor Supply Current:	t: 100mA	
Maximum Cable Length:	200m	
Recommended Cable:	4 core • overall screen	
Maximum Cable L/R:	100μH/ohm (P)	

Order Reference: T X 2 1 4 1 . 3 1 0 . 0 1 CHANNEL CARD GROUP I  $\langle E_{X} \rangle$ 

- Please specify:
- Measuring range 0...2mV
- Measuring range 0...5mV
- Measuring range 0...5mV
   Measuring range 0...10mV
- Measuring range 0...50mV
- Measuring range 0...100mV
- Measuring range 0...1V
- Measuring range 0...2V
- Measuring range Specific Voltage

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PART 1
4. TX2141
CHANNEL CARDS

#### 4.2 PULSE FREQUENCY INPUT CHANNEL CARD.

**4.2.1** TX2141.401 Pulse/frequency input







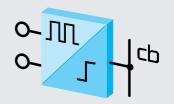
PART 1 4. TX2141 CHANNEL CARDS

#### 4.2.1 TX2141.401 CHANNEL CARD

- Pulse frequency signals from switches, proximity sensors, photocells and pulse wheels, frequency generators.
- Two independent inputs for function options.
- **■** Frequency range: 0...10kHz.
- Programmable for: counting, pulse interval, pulse frequency, differential frequency, percentage pulse comparison, slip frequency, differential slip.



pulse/frequency signals



Connections:			
(Channel A)	A1	A1	A1
Input Signal  +V Present  OV Absent	2a 4a  1a 3a  P1 P2  2 2	2a 4a  1a 3a  P1 P2	2a 4a  1a 3a  P1 P2  2 2
		NAMUR proximity sensors     DIN 19234	
	• Input switches (section 12.2.2 D1 ).	Discrete fault alarm generated for OPEN CIRCUIT and SHORT CIRCUIT line condition. (section 12.2.2 ].	• Solid state or photocell input (section 12.2.2 D1).
Field Device Current (FI):	Insignificant	2mA per NAMUR	Insignificant

	TX2141.401.01	
Channel Card Current (CI):	30mA	
Maximum Cable L/R:	100μH/ohm (P)	
Maximum Cable Length:	500m	
Recommended Cable:	2 core • overall screen (per input)	
Sensor Voltage:	8.2V	
Frequency Range:	010kHz	

Order Reference: T X 2 1 4 1 . 4 0 1 . 0 1 CHANNEL CARD GROUP I  $\langle \xi x \rangle$ 

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#### PART 1 4. TX2141 CHANNEL CARDS

#### 4.3 ONOFF/STATE INPUT CHANNEL CARD.

4.3.1	TX2141.501	Dual NAMUR inputs	0-11-cp
4.3.2	TX2141.502	Dual Switch inputs with line monitoring	0 1 tp
4.3.3	TX2141.503	Dual Current state change inputs	0 1 tp
4.3.4	TX2141.504	Quad Switch inputs	7





PART 1 4. TX2141 CHANNEL CARDS

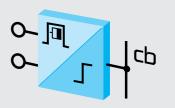
#### TX2141.501 CHANNEL CARD 4.3.1

- Change of state signals.
- Two independent inputs for NAMUR sensor inputs.
- Two independent inputs for simple ON/OFF switches.



#### **DUAL DIGITAL INPUT**

**NAMUR** inputs



(Channel A)  A1 A2  2a 4a  Input Signal  +V Present  OV Absent  A1 A2	2a 4a   2a 4a     1a 3a   1a	Connections:		
• Discrete FAULT alarm generated for OPEN  ON/OFF switches. (section 12.2.3 D1).	(section 12.2.3 <b>[F</b> ]).	(Channel A)  Input Signal  +V Present	2a 4a  1a 3a  2 x NAMUR proximity sensors to DIN 19234.  • Discrete FAULT alarm generated for OPEN	2a 4a  1a 3a  2    • Can also be used with 2 x conventional

	TX2141.501.01	
Channel Card Current (CI):	15mA	
Maximum Cable L/R:	100µH/ohm №	
Maximum Cable Length:	500m	
Recommended Cable:	2 core • overall screen (per input)	
Supply Voltage:	8.2V	
Max Switch Frequency:	10Hz	

T X 2 1 4 1 . 5 0 1 . 0 1 CHANNEL CARD GROUP I (Ex) Order Reference:

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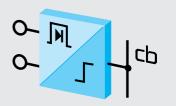
PART 1 4. TX2141 CHANNEL CARDS

#### 4.3.2 TX2141.502 CHANNEL CARD

- Change of state signals.
- Two independent inputs for simple ON/OFF switches with sensor line monitoring.

#### DUAL DIGITAL INPUT

Switch inputs with line monitoring



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Connections:	
(Channel A)  Input Signal  +V Present  OV Absent	Switches with series diode  Detection of SHORT CIRCUIT switch line, with series diode Detection of OPEN CIRCUIT switch line also, when contact shunt resistor is added  Discrete FAULT alarms generated for OPEN CIRCUIT and SHORT CIRCUIT line condition (section 12.2.3   T)
Field Device Current (FI):	1mA per location

	TX2141.502.01
Channel Card Current (CI):	15mA
Maximum Cable L/R:	100μH/ohm (P)
Maximum Cable Length:	500m
Recommended Cable:	2 core • overall screen (per input)

Order Reference: T X 2 1 4 1 . 5 0 2 . 0 1 CHANNEL CARD GROUP I Ex





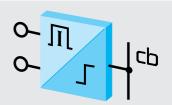
PART 1 4. TX2141 CHANNEL CARDS

#### 4.3.3 TX2141.503 CHANNEL CARD

- Change of state signals.
- Two independent inputs for sensors with current STATE CHANGE for fire and gas applications, smoke, flame, breakglass, etc.

#### **DUAL DIGITAL INPUT**

**Current state inputs** 



Connections:	
(Channel A)  Input Signal  +V Present  OV Absent	A1 A2  2a 4a  1a 3a  • Discrete FAULT alarms generated for OPEN CIRCUIT or SHORT CIRCUIT condition (section 12.2.3 ) • Current level state change. Normal: Less than 8mA Alarm: More than 20mA • Maximum number of loop devices: 25 (P)
Field Device Current (FI):	Insignificant.

	TX2141.503.01
Channel Card Current (CI):	30mA
Maximum Cable L/R:	100μH/ohm (P)
Maximum Cable Length:	500m
Recommended Cable:	2 core • overall screen (per input)

Order Reference: T X 2 1 4 1 . 5 0 3 . 0 1 CHANNEL CARD GROUP I

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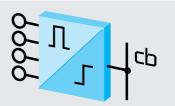
PART 1 4. TX2141 CHANNEL CARDS

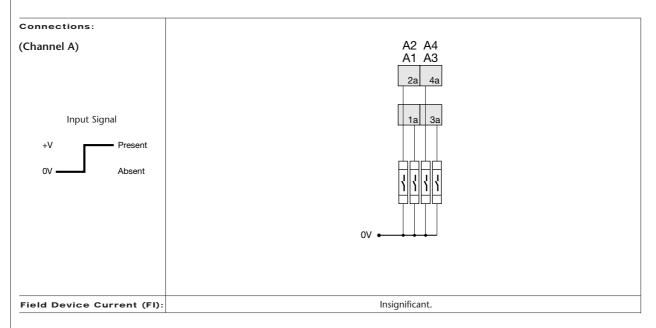
#### 4.3.4 TX2141.504 CHANNEL CARD

- Change of state signals.
- Four independent inputs for simple ON/OFF switches.
- Limit switches, pressure switches, level switches, etc.

#### QUAD DIGITAL INPUT

Switch inputs

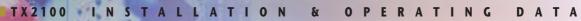




	TX2141.504.01
Channel Card Current (CI):	15mA
Maximum Cable L/R:	100μH/ohm
Maximum Cable Length:	500m
Recommended Cable:	2 core
Max Switch Input Voltage:	MUST be sourced from the SAME Intrinsically Safe power supply.
Max Switch Frequency:	10Hz

Order Reference: T X 2 1 4 1 . 5 0 4 . 0 1 CHANNEL CARD GROUP I  $\langle \xi_{X} \rangle$ 

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PART 1 4. TX2141 CHANNEL CARDS

#### 4.4 ONOFF/STATE OUTPUT CHANNEL CARDS.

4.4.3 TX2141.603 Quad Solid State Output

4.4.4 TX2141.604 Dual Relay Output





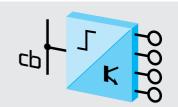
PART 1 4. TX2141 CHANNEL CARDS

#### 4.4.3 TX2141.603 CHANNEL CARD

- Four individual open collector solid state NPN switches.
- Output Rating: 400mA at 24V dc max.

#### QUAD ONOFF/STATE OUTPUT

solid state switch



Connections: (Channel A) A2 A4 A1 A3 Selectable for the preferred • 0V failsafe RESET STATE: OUTPUT CIRCUIT CLOSED (ON) **OUTPUT CIRCUIT CLOSED (OFF)** • Each output circuit is current limited to protect against short circuit conditions. • An alarm warning will be generated if a switching failure occurs (section 12.2.4 🕝 ) (section 12.2.4 🔳 ) Field Device Current (FI): Insignificant.

	TX2141.603.01
Max Load Voltage:	MUST be sourced from the SAME Intrinsically Safe power supply.
Max Load Current:	100mA.
Output Voltdrop:	Less than 1V.
Channel Card Current (CI):	30mA

Order Reference: T X 2 1 4 1 . 6 0 3 . 0 1 CHANNEL CARD GROUP I  $\langle \xi \chi \rangle$ 

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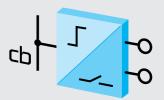
PART 1 4. TX2141 CHANNEL CARDS

#### TX2141.604 CHANNEL CARD 4.4.4

- Two individual medium duty relays.
- Voltage free output contacts.
- Contact Rating: 2A 30V ac/dc.
- Contact Format: 1 N/O on each relay.
- Galvanically isolated output from the Commandbus.







Connections:	
(Channel A)	A1 A2
Programmable in the SETUP section for the preferred failsafe RESET STATE: (section 12.2.4 LB)	Standard contacts are wired NORMALLY OPEN  NB: Contacts can also be supplied wired as NORMALLY CLOSED to specification.
OUTPUT CIRCUIT CLOSED (ON)	1a 3a
OUTPUT CIRCUIT CLOSED (OFF)	<ul> <li>Relay shown de-energised – no power</li> <li>FAULT alarm generated if a relay operation failure is detected (12.2.4 )</li> </ul>
Field Device Current (FI):	Insignificant.

	TX2141.604
Max Contact Voltage:	30V ac/dc
Max Contact Current:	2A (resistive load)
Contact Format:	1 normally open
Channel Card Current (CI):	30mA
Isolation:	Output contacts are galvanically isolated

T X 2 1 4 1 . 6 0 4 . 0 1 CHANNEL CARD GROUP I  $\langle \xi_x \rangle$ Order Reference:

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#### INSTALLATION & OPERATING DATA

CONTROL & DISPLAY PRODUCT



PART 1
4. TX2141
CHANNEL CARDS

#### 4.5 ANALOGUE OUTPUT CHANNEL CARD.

**4.5.1 TX2141.701** Dual 4...20mA Output



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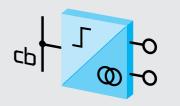
PART 1 4. TX2141 CHANNEL CARDS

#### 4.5.1 TX2141.701 CHANNEL CARD

- Two independent outputs.
- Output control for motorised valves, controllers, servo devices, process loops, inverters, recorders, speed controllers, heat controllers.
- 4...20mA repeater when driven from an analogue channel card.
- Can be data code driven when a specific program is installed in the Command module or from Modbus (LAN 1/LAN 2).



4...20mA



	TX2141.701.01
Channel Card Current (CI):	15mA
Output Signal:	420mA
Maximum Load:	400 ohms
Maximum Cable L/R:	Defined by the Intrinsically Safe load device.

Order Reference: T X 2 1 4 1 . 7 0 1 . 0 1 CHANNEL CARD GROUP I  $\langle \xi \chi \rangle$ 

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PART 1
4. TX2141
CHANNEL CARDS

#### 4.6 ACCESSORIES.

TX2141.08 Blank Channel Card to cover unused locations.



#### TX2141.09 Marking tag bar

Self-adhesive fixing to the TX2102 Terminal Module.
Supplied complete with 8 white tags for marking the specific duty reference of each channel.



#### 4.7 COMMANDER CONNECTING TERMINALS.

Commander modules are fitted with large size, high integrity screw terminals, housing captive spring clamping washers for ease of access, and security of connection even in conditions where vibration in present.

#### • Direct Connection

Two 2.5mm<sup>2</sup> conductors side by side.



#### • Crimp Connection

Two Bootlace crimps side by side or single Fork crimps: 6.5mm wide.



#### • Screwdriver

4mm Flatblade or size 1 Pozidrive.





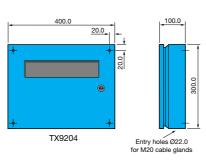
PART 1
4. TX2141
CHANNEL CARDS

#### 4.8 HOUSINGS FOR COMMANDER SYSTEMS.

#### TX9200 Series stainless steel Commander housings.

- Robust welded stainless steel construction.
- Mounting rails fitted.
- Observation window.
- Hinged cover with lockable fastening.
- Wall fixing facilities.
- IP66 environmental protection.









# 5 TX2131 commandbus convertor module



# TX2121 commandbus repeater module





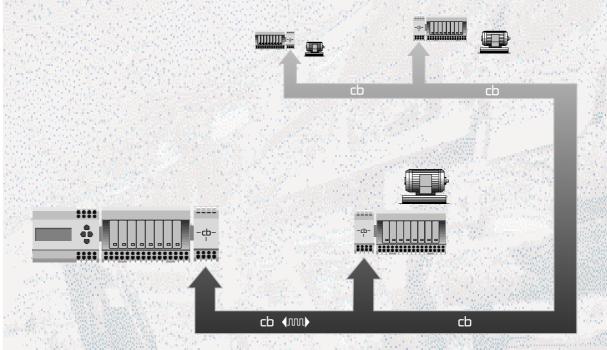
The TX2131 Convertor Module couples directly to the Commandbus and provides a hard wired conversion to screw terminal connections for cabling the Commandbus to Terminal Modules that are DISPERSED at some distance away.



# Data cable connection to a dispersed Terminal Module Cb (IMA)



5.2 Locally dispersed Commander system communicating data to and from a central Command Module



• Total line length (without repeaters) can be up to 1000m dependent upon application condition, or a maximum of 30 Terminal Modules.

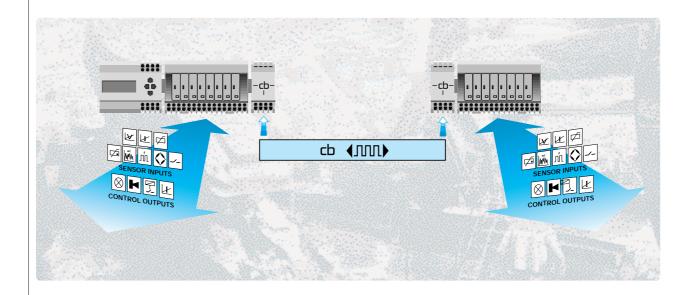


Power supply considerations (section 5.4)

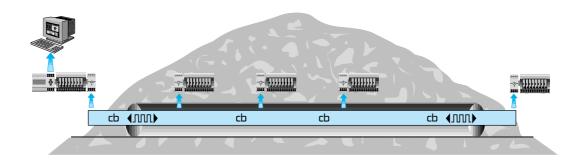


#### 5.3 A Commander System programmed to function in **Complementary Mode.**

I/O signals and data entering at one end of the system are directly replicated as I/O at the other end, using a single data cable.



A Commander system in complementary mode exchanging data and control signals along a tunnel.

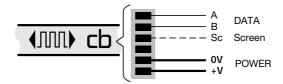


The transmission distance of the Commandbus may be increased at any point by using a TX2121 comms repeater module (section 5).

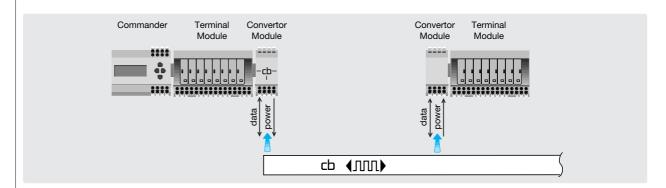


#### 5.4 Power Supply distribution to dispersed Commander Stations.

The dc power supply to energise a Commander System is normally an integral part of the Commandbus.



- Both data and power can be transmitted to dispersed Commander Stations.
- Recommended cable (with power): 2 twisted pairs Individually screened pairs, Collectively screened •
  BS 5308 pt1.
- The screen of the Commandbus is ultimately internally connected to the 0V terminal on the Command Module ONLY. Connect the Command Module 0V to a secure Earth at this point ONLY if required.



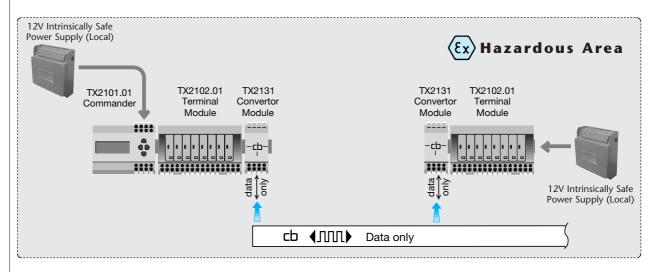
If independent power supplies are installed at EACH dispersed Commander station it means that the Commandbus cable can be reduced to 2 cores (1 twisted pair), as the +V and 0V power conductors are now eliminated. This fact can also, potentially, increase the transmitting distance because the supply voltage delivered to the Commander modules will be no longer influenced by volt drop in the run of interconnecting cable.

Larger scale systems can also be assembled now that the total power supply capability is not limited by the current capacity of the power supply at the Commander base station.

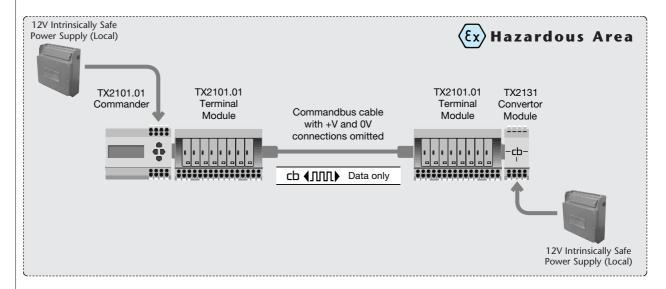
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Consequently, the channel capacity of a Commander system can be increased simply by omitting the power supply from the Commandbus cable and providing an independent IS Power Supply at each dispersed Commander station.



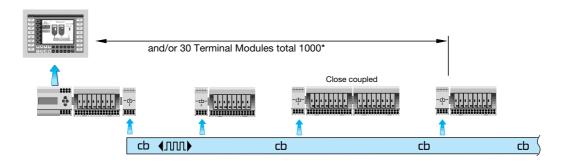
Even on non-dispersed Commander systems, where Commandbus convertor modules are not needed - the same principles can be employed to introduce multiple Intrinsically Safe power supplies where a single power supply will not drive the channel capacity required.



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#### 5.5 Transmission Distance of the Commandbus on dispersed Datalinks



#### **COMMANDBUS PARAMETERS**

• Physical layer: RS485 (Multidrop).

• Max. number of Terminal modules: 30 (subject to Ex restrictions).

• Maximum distance: 1000m TOTAL (without Commandbus repeaters).

#### CAUTION GROUP I Ex Systems



The method of power distribution to the Terminal Modules will be the predominant factor in maintaining operational safety in Hazardous Area systems.

POWER SUPPLY CONNECTIONS **MUST** BE OMITTED FROM **ALL** DATA CABLES. SO THAT ALL POWER SUPPLIES IN THE SYSTEM ARE INDIVIDUALLY SEGREGATED BY THE COMMANDBUS.

Our Commander application engineers will be pleased to advise and assist.

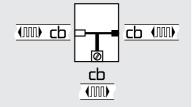




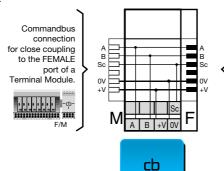
#### 5.6 TX2131 COMMANDBUS CONVERTOR MODULE



- Converts the Commandbus to screw terminal connections to enable cable connection runs to locally dispersed Commander systems.
- Internally hard-wired passive device.



#### Connections:



Commandbus connection for close coupling to the MALE port of a Terminal Module.

F/M



 The screen of the Commandbus is ultimately internally connected to the 0V terminal on the Command Module ONLY.

Connect the Command Module 0V to a secure Earth at this point ONLY if required.



 The Commandbus Convertor MUST only be connected to one port (M or F).
 Do not use it as a 'branch' connection.

Recommended Cable (with power):

2 twisted pair • Individually Screened • Collectively Screened • B5308 pt1

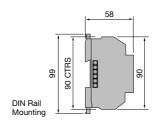
Recommended Cable (no power):

1 twisted pair • Collectively Screened • B5308 pt1

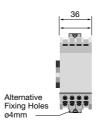
Maximum Power Supply Current:

6 Amps (system total).

#### Dimensions:



**(**/////)



All dimensions in mm.

Order Reference:

T X 2 1 3 1

COMMANDBUS CONVERTOR MODULE

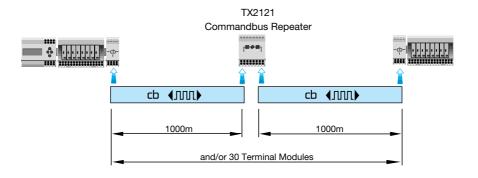
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#### **EXTENSION OF THE TRANSMISSION DISTANCE**

The transmission distance of a Commandbus link can be increased by incorporating a TX2121 Commandbus Repeater.

Each Repeater Module will increase the operating distance of the Commandbus by 1000 metres depending upon the cable and installation parameters.



The power supply for the Repeater Module can be derived from the Commandbus in the normal way, where system conditions permit. (Terminals +V and 0V on the Repeater Module).

THE POWER CONNECTIONS OF THE COMMANDBUS **MUST** BE OMITTED WHEN THE COMMANDBUS REPEATER IS LOCALLY POWERED.





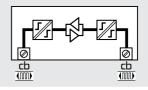
PART 1
5. TX2121
COMMANDBUS
REPEATER
MODULES

#### **TX2121.01 COMMANDER REPEATER MODULE**

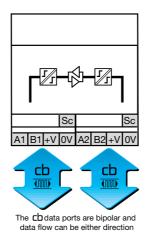
- Commandbus repeater with galvanic isolation.
- Increase distance on Commandbus networks.

#### **GROUP I**

isolated datacomms



#### Connections:





The module must be mounted in a protective metal housing (eg: TX9202 or TX9204).



The screen of the Commandbus is ultimately internally connected to the 0V terminal on the Command Module ONLY.

Connect the Command Module 0V to a secure Earth at this point ONLY if required.

Power Supply:	<ul> <li>12V on terminals +V and 0V (Can be derived from the Commandbus cable where operating conditions permit).</li> </ul>
	<ul> <li>Power can also be supplied locally from an approved 12V dc supply connected to terminals +V and 0V.</li> <li>THE POWER CONNECTIONS OF THE COMMANDBUS MUST BE OMITTED.</li> </ul>
Current Consumption:	50mA
Physical Layer:	RS485.
Protocol:	Trolex proprietary.
Additional (b) Distance:	1000m (Dependent upon cable and installation parameters).
Recommended Cable:	Twisted pair • Collectively Screened • B5308 pt1
Dimensions:	58 72 

Alternative Fixing Holes

Order Reference: TX2121.01 COMMANDBUS REPEATER MODULE. GROUP I

DIN Rail Mounting

**55** of 174

ISSUE F: 12/06

All dimensions in mm.



PART 1
5. TX2121
COMMANDBUS
REPEATER
MODULES

#### **COMMANDER SYSTEM DESIGN**

#### **Commandbus System Capacity**

• Maximum TERMINAL MODULES : 3

• Maximum CHANNEL CARDS :  $30 \times 8 = 240$ 

• Maximum LOCATIONS : ⊶ ☐ 240 x Single = 240 \

 $\approx 240 \times \text{Dual} = 480$  (or any combination of these)

240 x Quad = 960

**Maximum Cable Distance**: 1000m total line length without Commandbus repeaters

(dependent upon installation parameters)

A TX2121Commandbus Repeater will give a further

1000m distance.

#### **Commandbus Response Time**

Response time of a given Commander system configuration is approximately a function of the number of Terminal Modules in the network.

Response Time **Cb** = TERMINAL MODULES x 100 milliseconds

#### **System Architecture**

In practice, the structural architecture and operating distribution of a Commander system are both influenced by related technical parameters:

- The topology and distribution of the plant.
- The type of sensors and plant devices.
- The area classification of a system and hazardous area limitations.
- System power requirements and power distribution.
- The type of cable used for the databus.
- The overall resultant time response of the system.

Our Commander system application engineers can provide technical assessment of individual installation designs.



• Power supply considerations (section 5.4).



6. POWER SUPPLIES

# power supplies



#### AUDITING THE TOTAL SYSTEM CURRENT.

Before selecting a power supply, do a Commander System Current Audit. Summate the power requirement of all Commander Modules that are served by a single power supply.

Command Module (section 2)	
Terminal Modules (section 3.9)	
Commandbus Repeater Modules (section 5.6)	
TOTAL:	mA

PART 1
6. POWER
SUPPLIES

Several options of power supply are available to power Commander systems, the choice is dependent upon the type of system being installed:

#### 6.1 GROUP I $\langle Ex \rangle$ 12V dc.

- The TX6640 series of power supplies provides a stabilised 12V dc intrinsically safe power supply to power Group I Commander systems.
- Normally supplied in an Exd housing for mounting in the hazardous area
  or as a basic chassis version which can be fitted into an existing Exd housing.
  Both options can be supplied with integral 4-way isolating relay chassis in the
  Exd compartment for switching other hazardous area equipment (section 7).



DATA



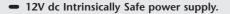
 Group I hazardous area Commander systems may need a power supply main isolator in order to comply with local regulations.







## 6.1.1 TX6641 POWER SUPPLY [Ex ia] TX6642 POWER SUPPLY Ex d [ia]

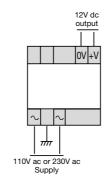


- TX6641 supplied loose in chassis form for fitting into existing Exd housings.
- TX6642 supplied in a Trolex Exd housing.
- Output current 1A.
- Available with 4-way isolating relay chassis for switching other Ex control circuits.
   (section 7)



GROUP I

Connections:





The module must be mounted in a protective metal housing when installed in a SAFE AREA.



The module must be mounted in a protective metal housing to an approved Exd standard when installed in a HAZARDOUS AREA.



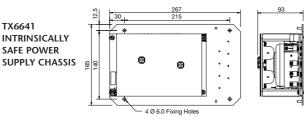
 The 12V dc supply only needs to be connected to the COMMAND MODULE.
 Power is distributed to the remainder of the system through the COMMANDBUS.



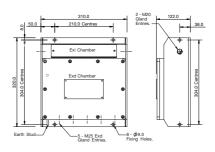
Power supply considerations (Section 5.4).

	See Technical Data Sheet TX6641 for full technical data.	
Output Relays:	Optional, 4-way output relay chassis. Clearance compatible for switching other Ex control circuits (section 7).	
Operating Temperature:	−20°C+55°C.	
Output Current:	1A	
Output Voltage:	+12V dc ±0.2V.	
Input Voltage:	110V ac • 230V ac	

#### Dimensions:



TX6642 INTRINSICALLY SAFE POWER SUPPLY IN EX d HOUSING



All dimensions in mm.

Order Reference:	T X 6 6 4 1 POWER SUPPL	Y CHASSIS	GROUP I (Ex)
Order Reference:	T X 6 6 4 2 POWER SUPPL	Y WITH Ex d HOUSING	GROUP I (Ex)

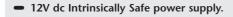
Please specify input voltage: • 110V ac (105

• 230V ac (106)

PART 1 6. POWER SUPPLIES

#### 6.1.2 TX6648 POWER SUPPLY Ex eq [ia] WITH BATTERY BACKUP

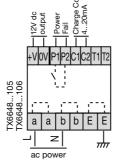




- TX6641 intrinsically safe power supply chassis supplied in a Trolex Ex q housing.
- Integral 3Ahr battery backup with automatic uninterrupted power transfer.
- Output current 1A.



#### Connections:





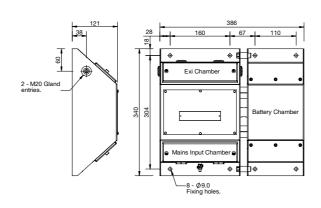
• The 12V dc supply only needs to be connected to the COMMAND MODULE. Power is distributed to the remainder of the system through the COMMANDBUS.



Power supply considerations (Section 5.4).

Input Voltage:	110V ac • 230V ac	
Output Voltage:	+12V dc ±0.2V.	
Output Current:	1A.	
Operating Temperature:	−20°C+55°C.	
Battery Backup:	Sealed lead/acid 3Ahr Max. Automatic uninterrupted power transfer.	
Condition Monitoring:	<ul><li>420mA output signal proportional to the charge level of the battery.</li><li>Output contact to indicate mains voltage absent.</li></ul>	
	See Technical Data Sheet TX6648 for full technical data.	

#### Dimensions:



All dimensions in mm.

Order Reference: **POWER SUPPLY** WITH Ex q HOUSING GROUP I

Please specify input voltage: • 110V ac (105)

• 230V ac (106)

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PART 1 6. POWER SUPPLIES

#### 6.1.3 TX6649 POWER SUPPLY Ex eq [ia] WITH BATTERY BACKUP



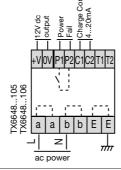
**GROUP** 



- TX6641 intrinsically safe power supply chassis supplied in a Trolex Ex q housing.
- Integral 20Ahr battery backup with automatic uninterrupted power transfer.
- Output current 1A.



Connections:





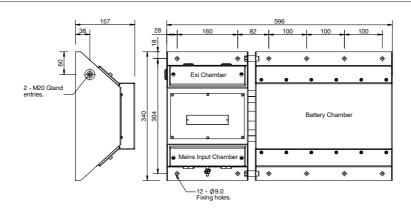
• The 12V dc supply only needs to be connected to the COMMAND MODULE. Power is distributed to the remainder of the system through the COMMANDBUS.



Power supply considerations (Section 5.4).

Input Voltage:	110V ac • 230V ac	
Output Voltage:	+12V dc ±0.2V.	
Output Current:	1A.	
Operating Temperature:	−20°C+55°C.	
Battery Backup:	Sealed lead/acid 20Ahr Max. Automatic uninterrupted power transfer.	
Condition Monitoring:	<ul><li>420mA output signal proportional to the charge level of the battery.</li><li>Output contact to indicate mains voltage absent.</li></ul>	
	See Technical Data Sheet TX6649 for full technical data.	

#### Dimensions:



All dimensions in mm.

Order Reference: TX6649 **POWER SUPPLY** WITH Ex q HOUSING **GROUP I** 

Please specify input voltage: • 110V ac (105)

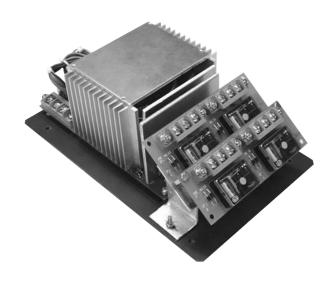
• 230V ac (106)

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PART 1
7. ISOLATING
RELAYS FOR
EXD (GROUP I)
INTERFACING

# isolating relays for Exd (Group I) interfacing



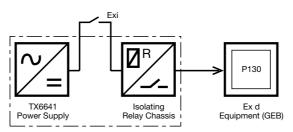


PART 1
7. ISOLATING
RELAYS FOR
EXD (GROUP I)
INTERFACING

## 7 ISOLATING RELAYS FOR Exd (GROUP I) INTERFACING

- When a Commander System is being used in a hazardous area it is sometimes necessary to switch field control devices which may not themselves be Intrinsically Safe. Some devices that are to be controlled may be housed in Ex d enclosures containing control circuits that may emanate from unspecified high voltage sources (section 6.2.1).
- Isolating relays may be combined with a TX6641 or TX6642 Power Supply. The operating coils of the relays are Intrinsically Safe and the contacts are clearance compatible for switching non-intrinsically safe apparatus or devices in separate Ex d enclosures (eg. P130 pilot circuits). A standard power supply chassis is fitted and wired with four independent relays with field connection facilities for coils and contacts.
- Isolating relay can also be provided fitted into independent Exq housings (TX6661).

#### Connections:



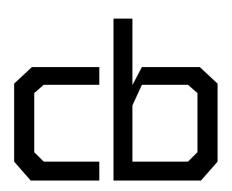
TX6641.19: Open Chassis version TX6642.19: Ex d Housing version

	TX6641.19	TX6642.19	TX6661		
Quantity of Relays:	4				
Contact Type:	One Changeover.				
Contact Rating:	5A at 375V peak.				
Coil Resistance:	460 Ohms.				
Coil Voltage:	12V.				
Current Consumption:	26mA.				
Format:	Open Chassis (section 6.2.1)	Ex d Housing (section 6.2.1)	Exq Housing		
	The module must be mounted in a protective metal housing when installed in a SAFE AREA (eg: TX9202 or TX9204).  The module must be mounted in a protective metal housing to an approved Exd standard when installed in a HAZARDOUS AREA.				



PART 1
B. COMMANDBUS
CABLES

8 commandbus cables





PART 1 B. COMMANDBUS CABLES  Commander modules are designed to be conveniently close coupled together on a standard DIN rail using the integral Commandbus connecting system.

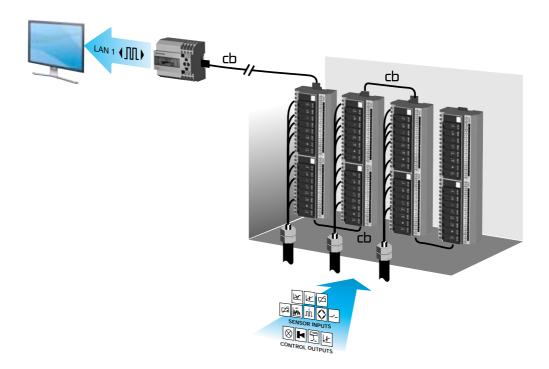


 Commandbus cables may be used to extend to locally dispersed Commandbus groups:



 Control panel wiring can be almost eliminated by connecting incoming field cables directly to the Commander terminal modules.

Control room cabling can also be simplified by using the Commandbus communication to interface with display systems.



CAUTION • Power Supply Considerations (Section 5.4).

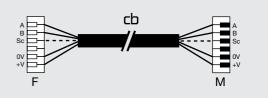


PART 1
B. COMMANDBUS
CABLES

#### 8.1 COMMANDBUS CABLES



Interconnecting cables and connectors for locally dispersed
 Commandbus systems.



#### Order Reference:

#### T X 2 1 5 1 COMMANDBUS CABLE HEADER. MALE

(Internal screw terminal connections). The housing of the connector is fitted with two retaining screws for anchoring to the TX2104 Series Command Modules, panel mounting version.



T X 2 1 5 2 COMMANDBUS CABLE HEADER • FEMALE

(Internal screw terminal connections)



T X 2 1 5 3 COMMANDBUS CABLE HEADER • MALE

(Internal screw terminal connections)



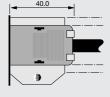
TX2154 6 CORE (5 used) COMMANDBUS CABLE

(For use with TX2151, TX2152 and TX2153)



T X 2 1 5 8 DIN RAIL END CLAMP





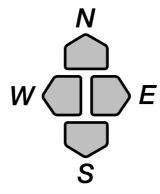
T X 2 1 5 9 END CLAMP WITH CABLE ANCHOR

Commandbus cable headers can be secured in position by using the retainer provided on this end clamp



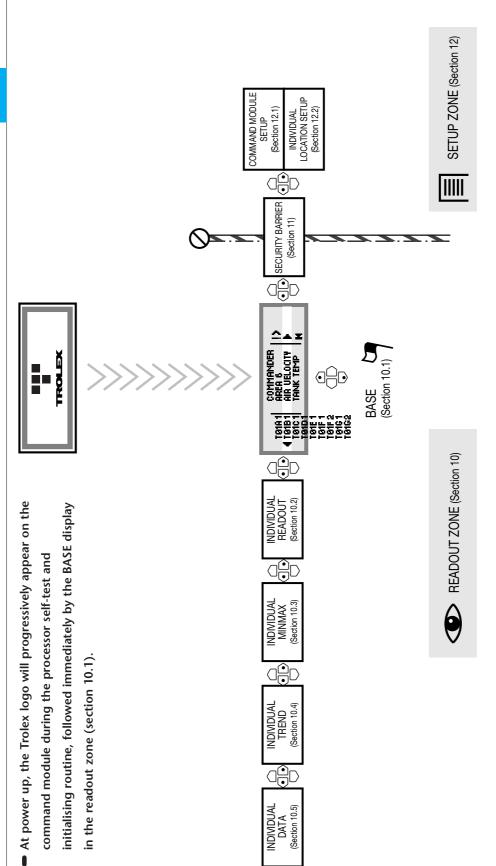


# 9 navigator map





PART 1
9. NAVIGATOR
MAP



Each key operation will click:

W F

■ Traverse the Navigator Map using the NAVIGATOR KEYPAD.





PART 1 10. READOUT readout zone



COMMANDER AREA 6 AIR UELOCITY TANK TEMP

T01A1 1 T01B1

Dual channel card-

Dual channel card-



PART 1
10. READOUT ZONE

#### readout zone



The Command Module will display CURRENT data relating to the input signals, or the output driver signals, at each LOCATION.



#### 10.1 BASE

The BASE readout will show the current data about the first items in the list of locations:

T O1B1 : Location address.

AIR UELOCITY: Duty text (section 12.2.1 ).

: An alarm setpoint is ON (section 12).

: Cursor indicating direction to READOUT ZONE.

: Cursor indicating direction to SETUP ZONE.

: Over range input signal.

: Under range input signal.

: HIGH fault.

: LOW fault.

: Channel card STATUS is EXCLUDE (section 12.2.1).

: Scan failure.

Unused locations will not appear in the BASE READOUT.

: Scroll **N/S** to a selected location.

: Key and hold for rapid auto keying.



TROLEX

#### 10.2 INDIVIDUAL READOUT

Step W for a more detailed readout of a selected location.

: Location address (Terminal module '01'/LOCATION 'B1').

AIR UELOCITY: Duty text (section 12.2.1 \bigsilon).

I : Type of channel card (section 4).

25m/s : Signal status with units (section 12.2.1).

: Bar graph of input signal STATIC.

Bar graph of input signal INCREASING TENDENCY.

: Bar graph of input signal DECREASING TENDENCY.

Setpoint 1 marker (section 12.2.1) denoting an UNDER alarm. Setpoint 2 marker (section 12.2.1) denoting an OVER alarm.

: SETPOINT 1 activated (ON) (section 12.2.1).

: SETPOINT 2 activated (ON) (section 12.2.1).

1.0 : LOWER SCALE MEASURING value (section 12.2.1 \_\_\_).

30E : UPPER SCALE MEASURING value (section 12.2.1 ]).

: SETPOINT 1 value (section 12.2.1 | ). 8.25

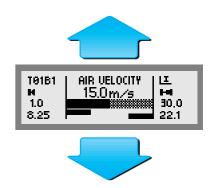
: SETPOINT 2 value (section 12.2.1 | ).

**EXC** : Channel card STATUS is EXCLUDE (section 12.2.1).

(5) : Scan failure.

Scroll N/S to other individual locations.





PART 1 10. READOUT ZONE

#### **UNDER RANGE/OVER RANGE INPUT**

Indication will be given if the input signal on a particular channel location transgresses beyond the normal operating range:

■ The Analogue input signal level is UNDER RANGE.



eg: Below 4mA

The Analogue input signal level is OVER RANGE.



eg: Above 20mA

#### FAULT INPUT

Indication will be given if the input signal on a particular channel location transgresses beyond 10% above or below the normal operating range.

A FAULT alarm state will also be initiated (section 12.2.1 / 12.2.2 / 12.2.3 / 12.2.4 / 12.2.5 **(7**):

■ The Analogue input signal level is LOW FAULT.



eg: Below 3.6mA

TOTAL AIR UELOCITY LE

TOTAL AIR UELOCITY LE

1.0

8.25

eg: Above 22mA

PART 1 10. READOUT

#### 10.3 INDIVIDUAL MINMAX

Step W for details of the MINIMUM and MAXIMUM measured values attained since last reset (section 12.2.1 🗘 ).

**AIR UELOCITY**: Duty text (section 12.2.1).

Maximum. Minimum.

AIR VELOCITY TØ1B1 3946 24.9m/s ^ 0.1 m/s 🗸

**AIR UELOCITY** 

9946

T01B1

#### 10.4 INDIVIDUAL TREND



Step W for historical trend graph (Hold for accelerated stepping).

AIR UELOCITY: Duty text (section 12.2.1).

3946 : Log number.

: Setpoint 2 (section 12.2.1).

: Setpoint 1 (section 12.2.1).

: Cursor (section 10.5).

: Zero baseline.

: Century marker. The display graph represents 100 logged readings. Each increment represent the next 100 readings. Total maximum logged readings: 4000.



Scroll N/S to TRAVERSE the cursor (Key and hold for self scrolling).



- Setpoint 1 and Setpoint 2 are PRESENT values only.
  - When the cursor reaches one of the extremities of a display field it will transfer to the mid-point of the succeeding display field.

#### 10.5 INDIVIDUAL DATA



Step W for details of the data present at the cursor position selected (section 10.4).

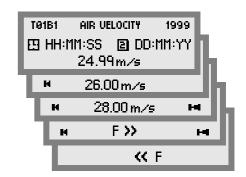
This data is recorded in the log (section 12.1.5).

(Key and hold for scroll).

Additional EVENT data is also displayed and recorded as shown.

Fault condition.

Alarm event.





Step E to return.

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ISSUE F: 12/06





security barrier



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PART 1 11. SECURITY

# security barrier



Attempts to step EAST into the SETUP ZONE will be halted if the security barrier is closed. Enter the KEYCODE to open the barrier:



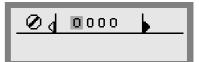
Scroll *E/W* to TRAVERSE the digits.



Scroll N/S to CHANGE the digits.



Step E to PASS into the setup zone.





This routine will not appear if the security barrier is open (section 12.1.1).

setup zone



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ISSUE F: 12/06



# setup zone



The fundamental operating characteristics of the Commander System can be SETUP as preferred.

The first SETUP task is:

#### 12.1 COMMAND MODULE SETUP

followed by

## 12.2 INDIVIDUAL LOCATION SETUPS





ENTER THE REQUIRED SETUPS BY USING THE COMMAND

MODULE NAVIGATOR KEYPAD





Conventions during the SETUP routines:



Step *E* to CONFIRM data (followed by AUTOMATIC RETURN to menu).

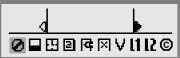


Step W to EXIT data.



Step W to RETURN to BASE.









The complete setup can also be installed directly into the Command Module through the LAN 1 or LAN 2 data ports, using the TX2199 Commander Configuration Software Package (section 13).





# 12.1 COMMAND MODULE SETUP





Starting from BASE (section 10.1).



Scroll N/S to COMMANDER.



Step **E** to the COMMAND MODULE setup.



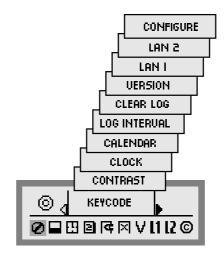
The security barrier may be closed at this point and deny access.



Scroll the cursor *E/W* to SELECT.



Step N to CONFIRM.



12.1.1







#### 12.1.1 SECURITY KEYCODE

- Close or open the security barrier.
- Enter a security code.



Scroll N/S to CLOSE/OPEN the security barrier.



Step E/W to TRAVERSE the digits.



Scroll N/S to CHANGE the digits.



Step E to CONFIRM.



#### 12.1.2 DISPLAY CONTRAST

The contrast of the LCD characters can be adjusted for best visual clarity.



Scroll N/S to ADJUST the level of contrast.



Step E to CONFIRM.



O 1234

1234



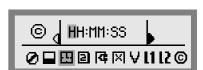
#### 12.1.3 CLOCK

Time information is used in the log record.



Step E/W to TRAVERSE Hours, Minutes, Seconds.

Scroll N/S to SET the time.







#### **CALENDAR**

The date information is used in the log record.



Step E/W to TRAVERSE Days, Months, Years.



Scroll N/S to SET the date.



Step E to CONFIRM.



The Clock and Calendar section is powered by a miniature lithium cell having a life expectancy in excess of 10 years.



#### 12.1.5 LOG INTERVAL

Readings of data for each location will be continuously recorded at predetermined intervals (section 10.5).

The interval is adjustable between 1 second and 999 minutes.



Step *E/W* to TRAVERSE the minutes and seconds.



Scroll *N/S* to SET the digits.



Step E to CONFIRM.



Range: 1 sec...999 minutes



ALSO • Periodic recorded data for each location:

- Location address
- Signal value with units
- Time and date
- Events recorded for each location:
  - **F** Fault condition
- The maximum number of readings per location is 4000.

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#### 12.1.6 **CLEAR LOG**

All data stored in the log (section 12.1.4) can be cleared from all channels simultaneously.



Scroll N/S for YES/NO.



Step E to CONFIRM.



Only PERIODIC log readings are cleared. \*\* EVENT log readings are permanently retained.



Always clear the log if any changes are made to the COMMAND MODULE SETUP or the LOCATION SETUP to avoid ambiguous data recording.

#### **12.1.7 VERSION**

Software version will be displayed.



Scroll N/S for data.





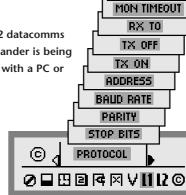
L1

#### 12.1.8 LAN 1 DATACOMMS

L2

#### 12.1.9 LAN 2 DATACOMMS

The protocol characteristics required for the LAN 1 and LAN 2 datacomms can be individually setup. This is only necessary where Commander is being integrated into a wider communication network, to interface with a PC or user display.



MON ASSIGN

Scroll N/S to SELECT.



Step *E* to ENTER.

#### PROTOCOL SELECTION

The standard communication protocol is MODBUS (BINARY).

A COMMANDER CONTROL option is also available for use with the TX2199 Commander Configuration Software Package (section 13) or for interfacing with special control programmes which may be installed in the Command Module.

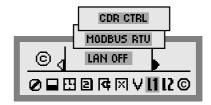
There is also an option to disable the LAN input completely when required.



Scroll N/S to SELECT.



Step E to CONFIRM.





Scroll *N/S* to DEFINE values



PROTOCOL	MODBUS	COMMANDER CONTROL		
Stopbits:	1/2			
Parity:	None/Odd/Even			
Baud Rate:	300/600/1200/2400/4800/9600 / 14K4/19K2/28K8/38K4/57K6/115K2			
Address	1 to 250 (protocol dependent)			
TX On:	0.1 – 99ms			
TX Off:	0.1 – 99ms			
Monitor Timeout:	OFF/1sec/5sec/10sec/30sec/60sec	<u> </u>		
Monitor Assign:	<b>1</b> T16A1 ✓			



#### **COMMUNICATIONS MONITOR**

The integrity of the LAN1/LAN2 MODBUS communication link can be monitored over successive periods. The period can be selected from 1 second up to 60 seconds or OFF.

If a communications failure is detected, an alarm can be assigned to any selected channel card location.

ASSIGNING A COMMS MONITOR FAILURE ALARM					
1	Т	10	В	1	<b>✓</b>
Assignation Identity  1	Constant	Destination Address	Channel Address	Input location at the channel address	Execution at the assigned destination
3	(Terminal module)	030	<u> </u>	Single	<b>√</b> :G0
4 5 6 7 8				Dual 10 Quad 10 3 8 8 8 9 9	X:RESET A latched output relay (section 12.2.4 M)
	(The setpoint is assigned to the Command Module for use in a specific program).				

# (C)

# CONFIGURE

When a Commander system has been assembled and loaded with channel cards, the Command Module must be instructed to scan the system to automatically identify (REFRESH) the type of card at each location and number of Terminal Modules fitted in that system.

The same goes for a system that has been modified.

To avoid confusion, this function is only executed when instructed to do so by the user.

FIXED: No REFRESH at any time.

REFRESH NOW: REFRESH when CONFIRMED from the keypad.

RFSH AT BOOT: REFRESH whenever the Commander system is switched ON.



Scroll N/S for YES/NO.







# 12.2 INDIVIDUAL LOCATION SETUPS





Starting from BASE (section 10.1).



Scroll N/S to selected LOCATION.

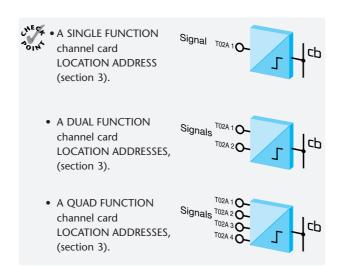


Step E to LOCATION setup.



نه The security barrier may be closed at this point and deny access (section 11).





The SETUP menu offered will vary depending upon which type of channel card is present at the location selected.











WECK

CONFIGURATION OF CHANNEL CARDS

Channel card locations are automatically identified and addressed by the Command Module dependent, upon the position that they take up in a Commander System (section 4).

To avoid confusion, this function is only executed when instructed to do so by the user (section 12 ©).



PART 1
12. SETUP ZONE
12.2.1



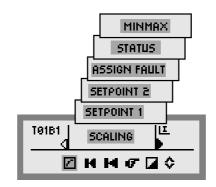
# 12.2.1 ANALOGUE INPUT CHANNEL CARDS



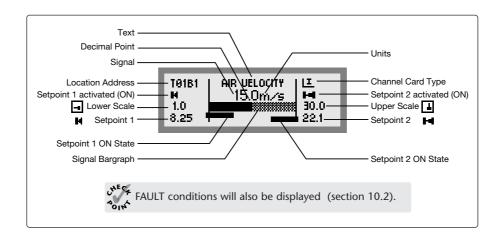


Scroll *E/W* to SELECT.







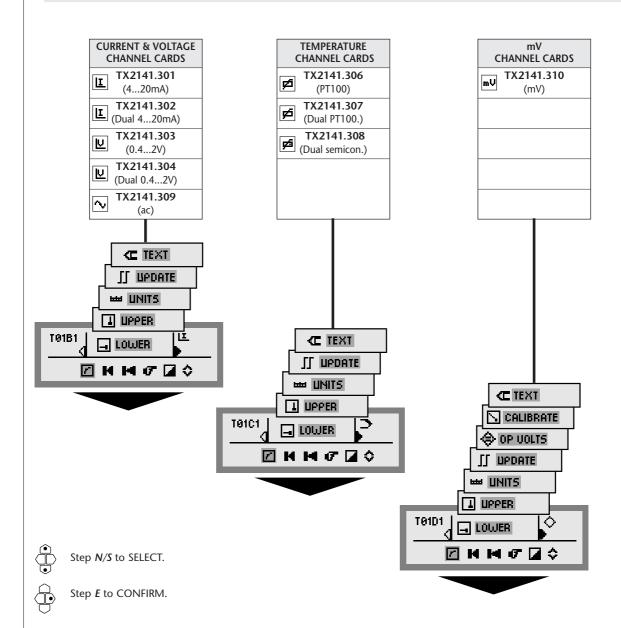


PART 1
12. SETUP ZONE
12.2.1



# SCALING

- **■** The various characteristics of the analogue input scale values can be determined.
- The setup menu offered will vary depending upon which ANALOGUE channel card is present at the location selected.







Lower



Upper

Independently adjustable, these two items are closely inter-related. They set the desired LOWER limit and UPPER limit of the display reading for a given magnitude of input signal span. This can be any numeric value and the polarity can be any negative value through to any positive value. The indicating 'range' from zero to full scale of the display can be programmed to show 'true' unit values incorporating multiplication factors or zero offset values.

This relates engineering units to the basic measured signal range.



Step *E/W* to TRAVERSE the cursor.



Scroll N/S to SCROLL the digits.



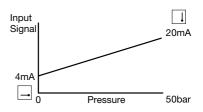
Step E to CONFIRM.



- The signal response between LOWER and UPPER will be assumed to
  - Signals from non-conforming devices such as temperature sensors will be automatically linearised to the appropriate standard.



Temperature channel cards, TX2141.306 / TX2141.307 / TX2141.308 will always measure the specified range. The VISIBLE DISPLAY range can be 'offset' if required (sections 4.1.6, 4.1.7 and 4.1.8).



DATA



Range: -9999.9 ... +9999.9 with decimal point

PART 1 12. SETUP ZONE **L** 



#### UNITS

A menu of standard engineering units is available for adding on to the signal value display to define the actual parameter being measured, eg. bar, mA, m/sec, °C, etc.



Scroll N/S to SELECT.



Step E to CONFIRM.

An option called USER will appear in the units menu choice.

Specific user defined units can be configured. Up to 4 digits of text can be entered into the display and there is a menu of letters, numbers and symbols to choose from.



Step *E/W* to TRAVERSE the characters.



Scroll N/S to SET.



Step E to CONFIRM.



For temperature cards only °C, °F and °K are offered.



## **UPDATE**

The INPUT SIGNAL is sampled at pre-determined intervals and the update time period is adjustable. Signal values are AVERAGED between samples.

A low setting will give rapid reaction to the input signal and higher settings may be entered where damping of a fluctuating input is necessary, or simply as a means of applying a delay to the input. This is particularly appropriate in electrically noisy environments.







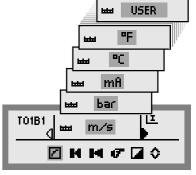
Step E/W to TRAVERSE the cursor.



Scroll N/S to SET the value.

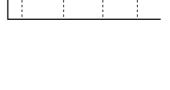


Step E to CONFIRM.



V, mV, A, mA, °C, °F, °K, g, kg, mbar, bar, Pa, kPa, PSI, %, ppm, %RH, mm, m, mm/s, m/s, m<sup>3</sup>/s, m<sup>3</sup>/m, m<sup>3</sup>/h, l/s, l/m, l/h, g/s, g/m, g/h, kg/s, kg/m, kg/h, rpm, pps, Hz, kHz, secs, mins, hrs,





**UPDATE** 

TIME



Range: 0.1 ... 60 seconds







# OUTPUT VOLTAGE

This additional item will appear in the menu when a mV input location is selected for SETUP.

The TX2141.312 channel card provides a regulated variable output current for powering sensors and strain gauges.

The output current may be set to concur with that of the sensing device being used (section 4.1.10).



Step *E/W* to TRAVERSE the digits.



Scroll N/S to SET the digits.



Step *E* to CONFIRM.



Range: 0...50mA



Adjust the current to the correct value using a suitable meter BEFORE connecting the sensor.



The output of the mV supply card is self regulating and will automatically limit if it is operated beyond its rated parameters.





## TEXT

Duty Text can be entered to denote the Input duty, the location or the tag reference of the input device.

Up to 12 digits of text can be entered into the display and there is a menu of Letters, Numbers and Symbols to choose from.



Step *E/W* to TRAVERSE the characters.



Scroll *N/S* to SET the characters.



Step E to CONFIRM.





A default message will appear if no user text is entered.





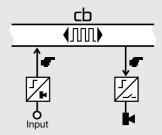


## SETPOINT 1



## SETPOINT 2

- Each input channel location has two individual SETPOINTS (SP1 and SP2) which can be activated ON for ALARM or CONTROL functions.
- The various operating response characteristics of each setpoint can be individually setup.
- Setpoint ON states are transferred onto the Commandbus and can be assigned to selected output driver channel locations to INITIATE field output actions.
- A setpoint that is activated ON = ALARM or CRITICAL condition.

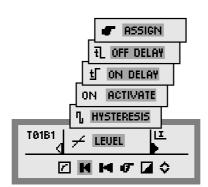




Step N/S to SELECT.



Step  $\boldsymbol{\mathit{E}}$  to CONFIRM.

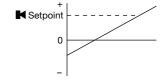


PART 1 12. SETUP ZONE 



#### LEVEL

The ON level of the setpoint can be setup. This can be set for any numerical value and the polarity can be positive or negative as required.



Scroll *E/W* to TRAVERSE the cursor.



Range limited to the LOWER and UPPER values setup (section )



Step E to CONFIRM.

Scroll N/S to SET the digit.

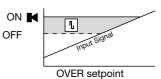


# HYSTERESIS

The Hysteresis is the DEADBAND between the setpoint ACTIVATING ON and ACTIVATING OFF as the input signal increases and decreases.

The OFF level can be defined with respect to the ON setpoint (section 12.2.1 ON).





• OFF level values less than the ON level.



• OFF level values greater than the ON level.



Scroll *E/W* to TRAVERSE the cursor.



Scroll N/S to SET the digit.

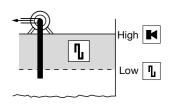


Step E to CONFIRM.

9999.9 HH G 🗷 🗘

A low value of hysteresis, is often used to override fluctuating signal levels and to prevent 'hunting' in closed loop control systems.

A high value of hysteresis can also be used as a control function as when controlling the operation of pumps. The pump will start at high level and continue pumping until low level is reached at the bottom of the hysteresis band.



PART 1
12. SETUP ZONE
12.2.1

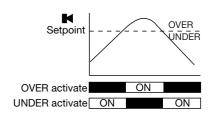


#### ON ACTIVATE

The setpoint can be setup to be activated ON when the input signal is OVER the setpoint level or activated ON when the input signal is UNDER the setpoint level.

For example; when monitoring overspeed on a conveyor, the setpoint can be set to be activated ON when the level of the input signal from the sensor is OVER the setpoint value to give a failsafe alarm function.

Conversely, when monitoring underspeed, the setpoint can be set to be activated ON when the input signal from the sensor is UNDER the setpoint.



Mrzo

Both modes can be combined using the two setpoints (SP1 and SP2) to provide boundary protection.



Step N/S to SELECT.



Step E to CONFIRM.





#### ON DELAY



#### **OFF DELAY**

The activation ON of the setpoint can be delayed by an adjustable time period (t ON). This is useful for alarm verification, to apply time delay in a process control action, or to override a spurious fluctuation of the input signal.

The activation OFF of the setpoint can also be delayed by an adjustable time period (t OFF).

If the input signal recedes from the setpoint level before the time has elapsed, the timer will reset to zero, ready to start again.





Step *E/W* to TRAVERSE the digits.



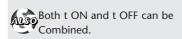
Scroll N/S to SET the time t.

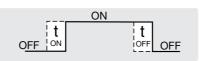


Step E to CONFIRM.



Range: 0 ... 255 seconds





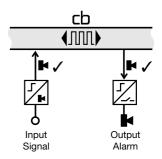
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# ASSIGN

- A SETPOINT ON state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/STATE output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step E/W to TRAVERSE the address.



Scroll *N/S* to SET ✓ or X.





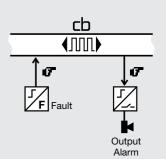
ASSIGNATIONS					
1	Т	10	В	1	✓
Assignation Identity	Constant	Destination Address	Channel Address	Input location at the channel address	Execution at the assigned destination
3	(Terminal module)	030	<b>B</b> -	Single 1 o Dual	<b>√</b> :G0
5 6				Quad	*:RESET  A latched output relay (section 12.2.4 M)
8			<b>Z-</b>		12.2.4 (M)
	(The setpoint is assigned to the Command Module for use in a specific program).				

PART 1 **12. SETUP ZONE** L G



# ASSIGN FAULT

- Each channel card location will give a common FAULT output state for:
  - Analogue input signal UNDER RANGE (section 10.2).
  - Analogue input signal OVER RANGE (section 10.2).
  - Analogue signal LOW FAULT (section 10.2).
  - Analogue signal HIGH FAULT (section 10.2).
  - Sensor fault.
  - Channel card fault.
- The FAULT state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/ output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.

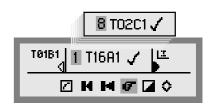


Step *E/W* to TRAVERSE the address.



Scroll *N/S* to SET ✓ or X.





ASSIGNATIONS					
1	Т	16	Α	1	<b>✓</b>
Assignation Identity  1 2 3 4 5 6	Constant  (Terminal module)	Destination Address	Channel Address  B - C - D - E E	Input location at the channel address  Single  Dual  Ouad	Execution at the assigned destination  Signature: GO  RESET A latched output relay (section 12.2.4 [M])
8	C (The setpoint is assigned to the Command Module for use in a specific program).				12.2.4 (W)





# STATUS

As a result of plant maintenance, it may be necessary to temporarily disable a particular channel card location.

The location can be properly EXCLUDED to prevent false alarm states occurring.



Scroll N/S to SELECT.



Step E to CONFIRM.





Reinstate INCLUDE after the interruption is over.



- Always EXCLUDE a channel card location when changing a channel • Always EXCLUDE a Charmer Card Total Control of Card otherwise the Command module will perceive a FAULT.
  - Remember that where a channel card that has been EXCLUDED and replaced, the new card will need to be first SETUP, INCLUDED and REFRESHED (section 12.2.1



PART 1
12. SETUP ZONE
12.2.1



## MINMAX

The maximum value and minimum value that the signal has reached since the last RESET, is stored.

Dangerously HIGH or LOW sensor conditions may have occurred previously and this feature enables historic trends to be examined (section 10.3).

Stored values of previous MIN and MAX can be RESET to the current value.





Scroll N/S for YES/NO.



Step E to CONFIRM.





Data will be recorded in the log (section 12.1.5 and section 9).

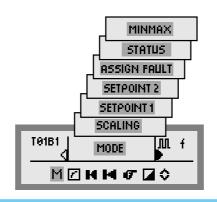


PART 1
12. SETUP ZONE
12.2.2

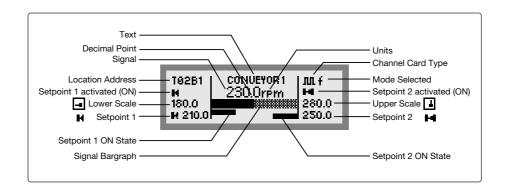
## 12.2.2 PULSE FREQUENCY INPUT CHANNEL CARDS









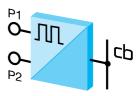






# MODE

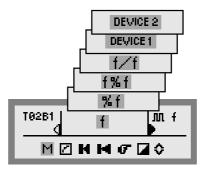
- This item will appear in the menu where a PULSE/FREQUENCY digital input channel card is present at a location.
- Each channel card has two inputs, P1 and P2, which are used in different ways depending upon which PULSE mode is selected.
- A pulse/frequency channel card can be setup into a choice of four different pulse processing modes. The first task is to determine which one is required before continuing with the SETUP.





Scroll N/S to SELECT.





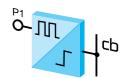
PART 1
12. SETUP ZONE
12.2.2

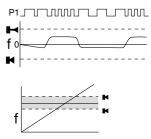
M
M



# **FREQUENCY**

- The FREQUENCY level or pulse rate on P1 is measured.
- P2 is not used.
- Speed monitoring, flow rates, etc.
- Each SETPOINT is determined as an ABSOLUTE frequency value.

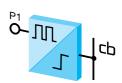


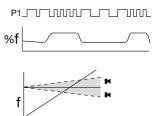




## % FREQUENCY

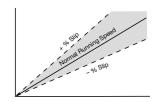
- The FREQUENCY level or pulse rate on P1 is compared with a FIXED frequency value that is entered If.
- P2 is not used.
- Each SETPOINT is determined as a PERCENTAGE frequency value.





- The PERCENTAGE FREQUENCY mode is most often used for monitoring the rotational speed of a machine shaft or speed measuring device by determining the pulse rate from a toothed wheel attached to the shaft and comparing it to a fixed reference speed.
- Overspeed or underspeed can be detected and is assessed as a percentage related to the NORMAL running speed (ie. 5% SLIP FREQUENCY or 5% UNDERSPEED).





PART 1
12. SETUP ZONE
12.2.2

M

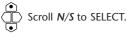


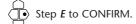
#### % FREQUENCY - continued

# If FIX f

The NORMAL running speed (f) of the machine or speed sensor must first be FIXED to be used as the base measuring reference.

This can be done in two ways:







#### CREATE

Create a base reference or NORM by entering a prescribed value of f.







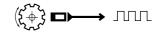


Range: 0 ... 999999 with decimal point

#### ADOPT

It is not always possible to know or measure the NORMAL running speed of a machine, or it may be difficult to establish the speed/pulse relationship, particularly where gearing or belts are being used.

If the machine is running at its normal speed at the time of setup, the resulting incoming frequency measured on P1 will be shown in the display. The value of f displayed can be ADOPTED as the base reference.





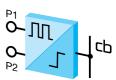


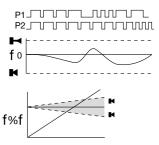
The value of f adopted can also be adjusted if required by returning to the CREATE mode.



#### PERCENTAGE DIFFERENTIAL FREQUENCY

- The FREQUENCY level or pulse rate on P1 is compared with the frequency level or pulse rate on P2.
- Speed comparison between two rotating components or frequency comparisons. Slip measurement on conveyors.
- Setpoints are determined as a PERCENTAGE difference between the two input frequencies with respect to the frequency on P1.

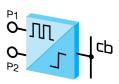


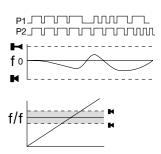




# **DIFFERENTIAL FREQUENCY**

- The FREQUENCY level or pulse rate on P1 is compared with the frequency level or pulse rate on P2.
- Setpoint levels are determined as an ABSOLUTE frequency difference.







# DEVICE 1 (P1)



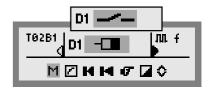
# DEVICE 2 (P2)

- Inputs P1 and P2 are normally configured to accept inputs from two NAMUR type sensors, also providing line fault monitoring of the sensors.
- Inputs P1 and P2 will also accept simple switch inputs such as reed switches or voltage levels. It is not possible to discriminate between genuine input signals and line faults on SWITCH inputs, so the appropriate fault alarms will be inhibited.



Scroll N/S to SELECT or



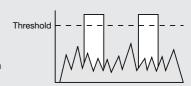


PART 1
12. SETUP ZONE
12.2.2



## **THRESHOLD**

- When a simple switch input is selected, voltage THRESHOLD adjustment will next be offered.
- The input signal threshold voltage level can be set so that only pulse amplitudes above a preset magnitude will be accepted by the input.
- Background noise or spurious interference can be eliminated in this way. This is particularly useful in a high speed, pulse processing system where a simple time delay on the pulse would be unacceptably slow.
- The default setting is 3.3V.





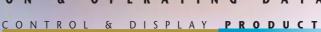
Scroll **N/S** to SET the value.





Range: 0.5 ... 7.1V











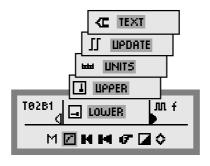
# SCALING

- **■** The various characteristics of the DIGITAL input scale values can be determined.
- The setup menu offered will also vary depending upon which PULSE MODE is selected for a channel card.

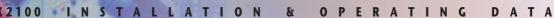


Step N/S to SELECT.











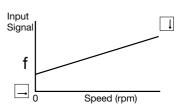


Lower



Upper

Independently adjustable, these two items are closely inter-related. They set the desired LOWER limit and UPPER limit of the display reading for a given magnitude of resultant frequency span. This can be any numeric value and the polarity can be any negative value through to any positive value. The indicating 'range' from zero to full scale of the display can be programmed to show 'true' unit values incorporating multiplication factors or zero offset values.





Step *E/W* to TRAVERSE the cursor.



Scroll N/S to SCROLL the digits.



Step E to CONFIRM.



Range: -9999.9...+9999.9 with decimal point.



PART 1 **12. SETUP ZONE** 12.2.2 M C



#### UNITS

A menu of standard engineering units is available for adding on to the signal value display to represent the actual parameter being measured, ie. Hz, I/m, m/sec, etc.



Scroll N/S to SELECT.



Step E to CONFIRM.

An option called USER will appear in the units menu choice. Specific user defined units can be configured. Up to 4 digits of text can be entered into the display and there is a menu of letters, numbers and symbols to choose from.



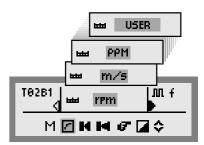
Step *E/W* to TRAVERSE the characters.



Scroll N/S to SET.



Step E to CONFIRM.



#### Menu:

V, mV, A, mA, °C, °F, °K, g, kg, mbar, bar, Pa, kPa, PSI, %, ppm, %RH, mm, m, mm/s, m/s, m<sup>3</sup>/s, m<sup>3</sup>/m, m<sup>3</sup>/h, l/s, I/m, I/h, g/s, g/m, g/h, kg/s, kg/m, kg/h, rpm, pps, Hz, kHz, secs, mins, hrs, USER.



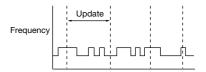


# **UPDATE**

Automatic dual measuring mode is employed for optimum accuracy.

At low frequency rates the processor will determine the frequency by measuring the period between successive pulses. It calculates an average over the selected update period.

At higher frequencies the processor counts the pulses and calculates the mean over the selected update period. The longer the update period, the more accurate the displayed reading.





Magnitude comparisons of each successive UPDATE will determine the status of the input signal.

**STABLE INCREASING** DECREASING



Step *E/W* to TRAVERSE the cursor.



Scroll N/S to SET the value.





Range: 0.1 ... 60 seconds









# TEXT

Duty Text can be entered to denote the Input duty, the location or the tag reference of the input device.

Up to 12 digits of text can be entered into the display and there is a menu of Letters, Numbers and Symbols to choose from.



Step  $\boldsymbol{E}/\boldsymbol{W}$  to TRAVERSE the characters.



Scroll **N/S** to SET the characters.



Step E to CONFIRM.



A default message will appear if no user text is entered.





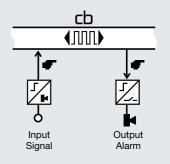


#### SETPOINT 1



#### **SETPOINT 2**

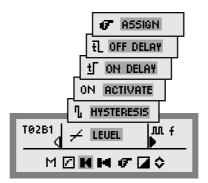
- Each input channel location has two individual SETPOINTS (SP1 and SP2) which can be activated ON for ALARM or CONTROL functions.
- The various operating response characteristics of each setpoint can be individually setup.
- Setpoint ON states are transferred onto the Commandbus and can be assigned to selected output driver channel locations to INITIATE field output actions.
- A setpoint that is activated ON = ALARM or CRITICAL condition.





Step N/S to SELECT.



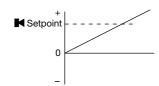






#### LEVEL

The ON level of the setpoint can be setup.





Scroll *E/W* to TRAVERSE the cursor.



Scroll N/S to SET the digit.



Step  $\boldsymbol{\mathit{E}}$  to CONFIRM.



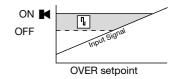
# 1

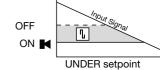
#### **HYSTERESIS**

The Hysteresis is the DEADBAND between the setpoint ACTIVATING ON and ACTIVATING OFF as the input signal increases and decreases.

The OFF level can be defined with respect to the ON setpoint (Section 12.2.2 **ON** ).

• OFF level values less than the ON level.





• OFF level values greater than the ON level.



Scroll *E/W* to TRAVERSE the cursor.



Scroll N/S to SET the digit.



Step E to CONFIRM.

A low value of hysteresis, is often used to override fluctuating signal levels and to prevent 'hunting' in closed loop control systems.





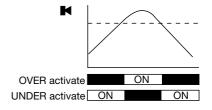


#### ON ACTIVATE

The setpoint can be setup to be activated ON when the input signal is OVER the setpoint value or activated ON when the input signal is UNDER the setpoint value.

For example; when monitoring excess speed or high frequency, the setpoint can be set to be activated ON when the level of the input signal from the sensor is OVER the setpoint value to give a failsafe alarm function.

Conversely, when monitoring flow failure or under speed, the setpoint can be set to be activated ON when the input signal from the sensor is UNDER the setpoint.





Step N/S to SELECT.



Step E to CONFIRM.



Both modes can be combined using the two setpoints (SP1 and SP2) to provide boundary protection.



#### **ON DELAY**



#### OFF DELAY

The activation ON of the setpoint can be delayed by an adjustable time period (t ON). This is useful for alarm verification, to apply time delay in a process control action, or to override a spurious fluctuation of the input signal.

The activation OFF of the setpoint can also be delayed by an adjustable time period (t OFF).

If the input signal recedes from the setpoint level before the time has elapsed, the timer will reset to zero, ready to start again.







Step E/W to TRAVERSE the digits.



Scroll N/S to SET the time t.

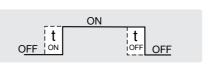


Step E to CONFIRM.



Range: 0 ... 255 seconds





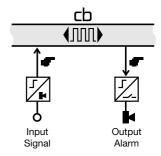
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#### **ASSIGN**

- A SETPOINT ON state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/STATE output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step *E/W* to TRAVERSE the address.



Scroll *N/S* to SET ✓ or X.





ASSIGNATIO	ASSIGNATIONS							
1	Т	12	Α	1	<b>√</b>			
Assignation Identity  1 2 3 4 5 6 7	Constant (Terminal module)	Destination Address	Channel Address  D-	Input location at the channel address  Single  Dual  Ouad  Ouad	Execution at the assigned destination  ✓:G0  X:RESET  A latched output relay (section 12.2.4 M)			
	(The setpoint is assigned to the Command Module for use in a specific program).							

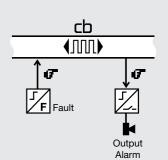
CONTROL & DISPLAY PRODUCT

PART 1 **12. SETUP ZONE** M F



### **ASSIGN FAULT**

- Each channel card location will give a common FAULT output state for:
  - Pulse/frequency signal UNDER RANGE (section 10.2).
  - Pulse/frequency signal OVER RANGE (section 10.2).
  - Sensor fault.
  - Channel card fault.
  - OPEN CIRCUIT switch line. NAMUR inputs only (section 12.2.2 D1 ).
  - SHORT CIRCUIT switch line. NAMUR inputs only (section 12.2.2 D1).
- The FAULT state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/ output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step E/W to TRAVERSE the address.



Scroll N/S to SET  $\checkmark$  or X.





ASSIGNATIONS								
1	Т	16	Α	1	<b>√</b>			
Assignation Identity  1	Constant	Destination Address	Channel Address	Input location at the channel address Single	Execution at the assigned destination			
3 4 5 6 7 8	(Terminal module)	030		Dual 1 Ouad 1 Ou	✓:G0  X:RESET  A latched output relay (section 12.2.4 M)			
	C (The setpoint is assigned to the Command Module for use in a specific program).		1	ı	ı			





# STATUS

As a result of plant maintenance, it may be necessary to temporarily disable a particular channel card location.

The location can be properly EXCLUDED to prevent false alarm states occurring.



Scroll N/S to SELECT.



Step E to CONFIRM.





Reinstate INCLUDE after the interruption is over.



- Always EXCLUDE a channel card location when changing a channel card otherwise the Command module will perceive a FAULT.
  - Remember that where a channel card that has been first EXCLUDED and replaced, the new card will need to be SETUP, INCLUDED and REFRESHED (section 12.2.1 )



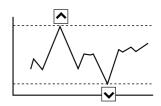


#### MINMAX

The maximum value and minimum value that the signal has reached since last RESET is stored.

Dangerously HIGH or LOW sensor conditions may have occurred previously and this feature enables historic trends to be examined (section 10.2).

Stored values of previous MIN and MAX can be RESET to the current value.





Scroll N/S for YES/NO.



Step E to CONFIRM.





Data will be recorded in the log (section 12.1.5 and section 9).



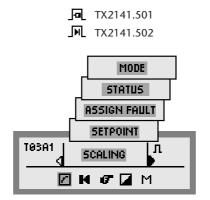
# 12.2.3 ONOFF/STATE INPUT CHANNEL CARDS

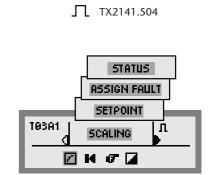
Step *E/W* to SELECT.

Step N to CONFIRM.



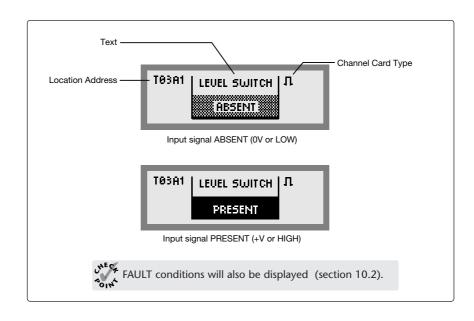
• The menu offered will vary depending upon which ONOFF/State input channel card is present at the location selected.





TX2141.503





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# TX2100 INSTALLATION & OPERATING DATA

CONTROL & DISPLAY PRODUCT

PART 1
12. SETUP ZONE
12.2.3
Π



# SCALING

**■** The update period and text can be determined.



Step N/S to SELECT.



Step E to CONFIRM.





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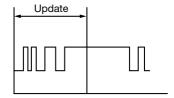




### UPDATE

The INPUT STATE is sampled at pre-determined intervals and the update time period is adjustable.

A low setting will give rapid reaction to the input signal and higher settings may be entered as a means of applying a delay to the input.





Step *E/W* to traverse the cursor.



Scroll N/S to SET the value.



Step E to CONFIRM.



Range: 0.1 ... 60 seconds



# TEXT

Duty Text can be entered to denote the Input duty, the location or the tag reference of the input device.

Up to 12 digits of text can be entered into the display and there is a menu of Letters, Numbers and Symbols to choose from.



Step *E/W* to TRAVERSE the characters.



Scroll N/S to SET the characters.



Step *E* to CONFIRM.





A default message will appear if no user text is entered.

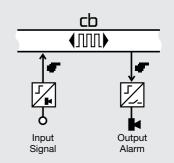


ПН



# SETPOINT

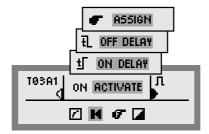
- Each input channel location has one SETPOINT (SP) which can be activated ON for ALARM or CONTROL functions.
- The various operating response characteristics of the setpoint can be individually setup.
- Setpoint ON states are transferred onto the Commandbus and can be assigned to selected output driver channel locations to INITIATE field output actions.
- **■** A setpoint that is activated ON = ALARM or CRITICAL condition.





Step N/S to SELECT.



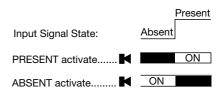






#### ON ACTIVATE

The setpoint can be setup to be ON when the input signal is PRESENT or ON when the input signal is ABSENT.



DATA



Step N/S to SELECT.



Step E to CONFIRM.





#### **ON DELAY**



#### **OFF DELAY**

The activation ON of the setpoint can be delayed by an adjustable time period (t ON). This is useful for alarm verification, to apply time delay in a process control action, or to override a spurious fluctuation of the input signal.

The activation OFF of the setpoint can also be delayed by an adjustable time period (t OFF).

If the setpoint goes to OFF before the time has elapsed, the timer will reset to zero, ready to start again.







Scroll N/S to SET the time t.





Range: 0 ... 255 seconds



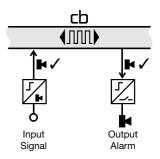






# ASSIGN

- A SETPOINT ON state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/STATE output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step *E/W* to TRAVERSE the address.



Scroll *N/S* to SET ✓ or X.





ASSIGNATION	ASSIGNATIONS								
1	Т	01	Α	2	1				
Assignation Identity  1	Constant	Destination Address	Channel Address	Input location at the channel address	Execution at the assigned destination				
3 4 5 6 7 8	(Terminal module)	030		Single  1 0 Quad  2 0 Quad  1 0 Quad  1 0 Quad  1 0 Quad	✓:G0  X:RESET A latched output relay (section 12.2.4 M)				
_	C (The setpoint is assigned to the Command Module for use in a specific program).								

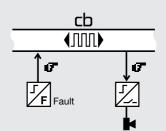
CONTROL & DISPLAY PRODUCT

PART 1
12. SETUP ZONE
12.2.3
Π



# **ASSIGN FAULT**

- **■** Each channel card location will give a common FAULT output state for:
  - OPEN CIRCUIT switch line. NAMUR inputs only (section 12.2.3 D1).
  - SHORT CIRCUIT switch line. NAMUR inputs only (section 12.2.3 D1).
  - Sensor fault.
  - Channel card fault.
- **■** The FAULT state is transferred onto the Commandbus.
- It can be ASSIGNED to a choice of up to 8 ONOFF/STATE output channel card location addresses.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Step *E/W* to TRAVERSE the address.



Scroll *N/S* to SET ✓ or X.





ASSIGNATIONS								
1	Т	16	Α	1	<b>✓</b>			
Assignation Identity  1	Constant	Destination Address	Channel Address	Input location at the channel address	Execution at the assigned destination			
3 4 5 6 7	(Terminal module)	030		Dual 10 Quad	✓:G0  X:RESET  A latched output relay (section 12.2.4 M)			
8	C (The setpoint is assigned to the Command Module for use in a specific program).		<u>"</u>					



# STATUS

As a result of plant maintenance, it may be necessary to temporarily disable a particular channel card location.

The location can be properly EXCLUDED to prevent false alarm states occurring.



Scroll E/W to SELECT.



Step 5 to CONFIRM.





Reinstate INCLUDE after the interruption is over.



- Always EXCLUDE a channel card location when changing a channel card otherwise the Command module will perceive a FAULT.
  - Remember that where a channel card that has been first EXCLUDED and replaced, the new card will need to be SETUP, INCLUDED and REFRESHED (section 12.2.3 )



#### MODE



- This additional item will appear in the menu when a TX2141.501 channel card is fitted.
- The input is normally configured to accept a signal from a standard NAMUR type sensor.
- The channel card will also respond to UNDERRANGE and OVERRANGE line conditions, occurring, by generating appropriate LOW FAULT or HIGH FAULT alarms (section 10).
- The input will also accept a simple SWITCH input, typically; pressure switches, limit switches, photocells etc.

It is not possible to discriminate between genuine input signals and line fault conditions on a SWITCH input, so the FAULT alarms will be automatically inhibited when this type of sensor is defined.

It will be necessary to SETUP which type of input device is being used.



Scroll *N/S* to SELECT — or — .





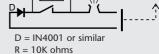


#### MODE



- This additional item will appear in the menu when a TX2141.502 channel card is fitted.
- The input is configured to accept an input from switching devices such as pressure switches, limit switches and thermostats, etc. with a diode connected in SERIES at the remote point.
- The channel card will also respond to a SHORT-CIRCUIT condition, occurring, by generating a HIGH FAULT alarm (section 10).
- Also connect a shunt resistor in PARALLEL with the switching device at the remote point and the channel card will also be able to DISCRIMINATE between a normal contact opening function and an OPEN-CIRCUIT line condition. An OPEN-CIRCUIT condition will generate a LOW FAULT alarm (section 10).





■ It will be necessary to SETUP the fact that a shunt resistor is being used.



Scroll N/S to SELECT + or + 1





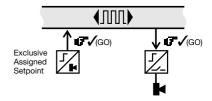




#### 12.2.4 ONOFF/STATE OUTPUT CHANNEL CARDS



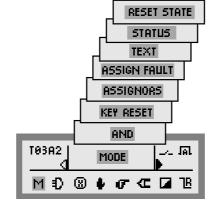
- An ONOFF/STATE OUTPUT channel card location is initiated when it recognises an exclusive GO command from the Commandbus.
- Each location will accept GO commands from any number of GO setpoints that may be setup and assigned to it from INPUT CHANNEL CARD LOCATIONS.



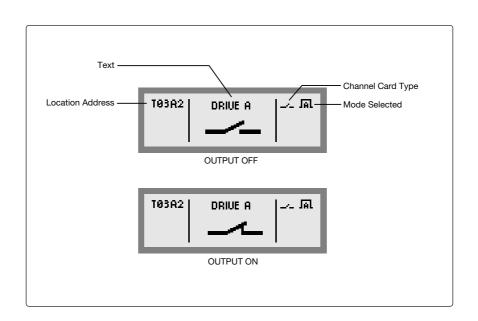


Step *E/W* to SELECT.













#### MODE

The output operating MODE can be setup.



Scroll N/S to SELECT.



Step *E* to CONFIRM.



#### AUTO RESET

 The channel will ACTIVATE when the GO command is PRESENT and RESET when the GO command is ABSENT.



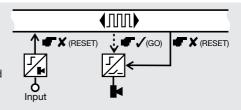
#### LATCH

 The channel will ACTIVATE when the GO command is PRESENT and LATCH until RESET.





- Each location will accept RESET commands from any number of RESET setpoints that may be setup and assigned to it from INPUT CHANNEL CARD LOCATIONS.



#### **Ⅲ** PULSE

 The channel will ACTIVATE when the GO command appears and RESET after an adjustable time.





Step  $\emph{E/W}$  to TRAVERSE the digits.



Scroll N/S to SET the time 't'.



Step *E* to CONFIRM.



Range: 0.1 ... 25 seconds



The RESET STATE of the output switching device can also be selected for the preferred failsafe condition (section 12.2.4 📳)

- Output circuit closed (ON) when RESET or
- Output circuit open (OFF) when RESET.



For failsafe reasons, the standard contact format is wired NORMALLY OPEN when the relay is de-energised. Contacts can be supplied wired NORMALLY CLOSED to specification, for alternative failsafe operation.





#### AND

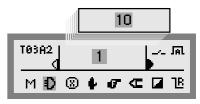
The output function can be set to initiate ONLY when several GO commands are present at the SAME TIME.



Scroll *N/S* to SET the number of GO commands required to initiate the output function.



Step *E* to CONFIRM.



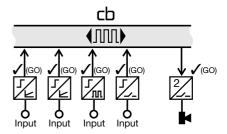
Range: 1 ... 10 simultaneous GO commands

#### **VOTING INPUTS**

This mode can also be used for VOTING inputs eg:

If GO commands are assigned to the output channel card location from say 4 other input channel cards, set the AND at 2.

The output will activate on a VOTE of any 2 out of 4.







#### **KEY RESET**

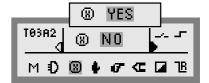
 A latched output switch can be reset from the Command module keypad if no GO signals are present.



Scroll N/S to for YES/NO.



Step E to CONFIRM.





# ASSIGNORS

Identify the origin and status of all setpoint GO or RESET commands that are assigned to this address from input channel card locations.



Scroll N/S to REVEAL assignors.



ASSIGNORS							
	Т	16	Α	1	: 1	[1]	<b>✓</b>
Incoming Setpoint Status	Constant	Source Address	Channel Address Source	Input location at the Source Channel Address	Setpoint at the Source	Assignation Identity	Execution
■ :0N — :0FF	(Terminal module)	030		Single  1 0 1 2 0 1 2 0 1 1 0 1 1 0 1 1 1 1 1 1	12	18	✓:G0  X:RESET A latched output relay (section 12.2.4 M)
	C (The setpoint originates from the Command Module).						
	LAN 1 LAN 2						

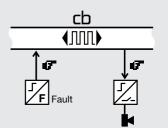
CONTROL & DISPLAY PRODUCT

PART 1
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12.2.4



#### ASSIGN FAULT

- **■** Each channel card location will give a FAULT output state for:
  - Output operation failure
  - Channel card fault
- **■** The FAULT state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/ output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step *E/W* to TRAVERSE the address.



Scroll N/S to SET  $\checkmark$  or X.





ASSIGNATIO	ASSIGNATIONS								
1	Т	16	Α	1	<b>✓</b>				
Assignation Identity  1 2 3 4 5 6 7	Constant (Terminal module)	Destination Address  030	Channel Address  D  D  F  F  H  H	Input location at the channel address  Single  Dual  Ouad  Quad	Execution at the assigned destination  ✓:G0  X:RESET  A latched output relay (section 12.2.4 M)				
	(The setpoint is assigned to the Command Module for use in a specific program).								

#### CONTROL & DISPLAY PRODUCT

PART 1 12. SETUP ZONE



#### **TEXT**

Duty Text can be entered to denote the Input duty, the location or the tag reference of the input device.

Up to 12 digits of text can be entered into the display and there is a menu of Letters, Numbers and Symbols to choose from.



Step *E/W* to TRAVERSE the characters.



Scroll N/S to SET the characters.



Step E to CONFIRM.



A default message will appear if no user text is entered.





#### **STATUS**

As a result of plant maintenance, it may be necessary to temporarily disable a particular channel card location.

The location can be properly EXCLUDED to prevent false alarm states occurring.



Scroll E/W to SELECT.



Step S to CONFIRM.



Reinstate INCLUDE after the interruption is over.



- Always EXCLUDE a channel card location when changing a channel card otherwise the Command module will perceive a FAULT.
- Remember that where a channel card that has been EXCLUDED and replaced, the new card will need to be first SETUP, INCLUDED and REFRESHED (section 12.2.3 )





# **RESET STATE**

The channel will ACTIVATE and RESET in response to commands from the Commandbus.

 For normal, failsafe alarm functions, the RESET STATE may be selected for: OUTPUT CIRCUIT CLOSED (ON).



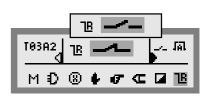
■ When the signal is being used to start drives, or to initiate machine functions, the RESET STATE may be selected for: OUTPUT CIRCUIT OPEN (OFF).





Scroll N/S to SELECT.



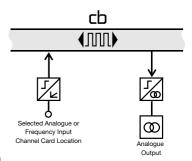






#### 12.2.5 ANALOGUE OUTPUT CHANNEL CARD

- Analogue output for driving motorised valve positioners, servo devices, process signal loops, invertors, recorders, speed controllers and heat controllers.
- Output signal standard: 4...20mA.
- The analogue output signal value can be controlled by any selected analogue or pulse/frequency input channel card location source as a signal repeater.
- The analogue output signal value can be controlled by programme data codes sourced from one of the LAN inputs on the Command module.

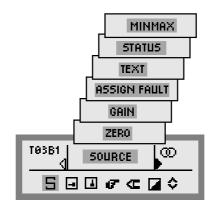




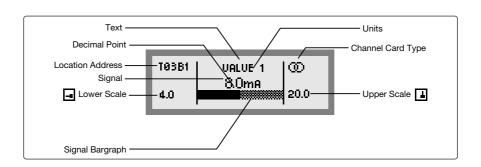
Step *E/W* to SELECT.



Step  ${\it N}$  to CONFIRM.







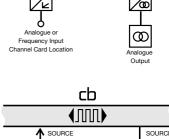
#### CONTROL & DISPLAY PRODUCT

PART 1
12. SETUP ZONE
12.2.5



# SOURCE

- The analogue output signal value can be determined from three optional control sources:
  - 1. The analogue input signal value generated by any selected input location on a channel card.
  - 2. LAN 1 / LAN 2.
  - 3. Data codes generated by values that are programmed into the command module when special control function software is installed in the Command module (section 13).
- All potential source addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.

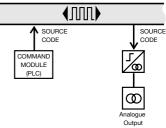


cb

**√**ЛЛЛ**▶** 

SOURCE

SOURCE





Scroll N/S to SELECT a channel card source or a LAN source.



Step *E* to CONFIRM.



Scroll N/S to SELECT the address identity available.





CHANNEL CARD SOURCE							
Т	T 16		1				
Constant	Source Address	Channel Address	Input location at the Channel Address				
(Terminal module)	030		Single  1 0 Ual  1 0 Quad  2 0 Quad  3 0 Quad  2 0 Quad  3 0 Quad  3 0 Quad  4 0 Quad  5 0 Quad  5 0 Quad  6 0 Quad  7 0 Quad  7 0 Quad  8 0 Quad  9 0 Quad  9 0 Quad  1 0 Quad				

LAN SOURCE
LAN 1
LAN 2
LAN1,2



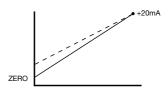
PART 1 **12. SETUP ZONE** 8



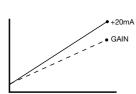
#### **OFFSET ZERO**

#### **OFFSET GAIN**

■ The value of the ZERO point can be OFFSET to match the characteristics of the field device.



■ The value of an analogue output level or GAIN can be OFFSET to match the characteristics of the field device and to compensate for any line losses.





Scroll N/S to change the analogue output signal until it complies with the requirement of the field device.



Range: ±10%



Step E to CONFIRM.



- Both OFFSET ZERO and OFFSET GAIN may be applied to an output signal.
  - The output signal will assume linearity between OFFSETS that are CONFIRMED.
  - OFFSET or GAIN adjustment may be extrapolated to an intermediate value of an analogue output signal.

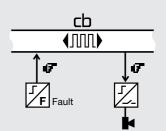
\_ - OFFSET GAIN OFFSET ZERO





#### **ASSIGN FAULT**

- **■** Each channel card location will give a common FAULT output state for:
  - Analogue output signal UNDER RANGE (section 10.2).
  - Analogue output signal OVER RANGE (section 10.2).
  - Channel card fault.
- The FAULT state is transferred onto the Commandbus.
- It can be SETUP to be ASSIGNED to a choice of up to 8 ONOFF/ output channel card location addresses to initiate action.
- All potential destination addresses available in the Commander system (including the Command Module) can be sequentially presented on the display and selected as desired.





Scroll N/S to SELECT the address identities available.



Step *E/W* to TRAVERSE the address.



Scroll *N*/*S* to SET ✓ or X.





ASSIGNATIONS								
1	Т	16	Α	1	<b>√</b>			
Assignation Identity	Constant	Destination Address	Channel Address	Input location at the channel address	Execution at the assigned destination			
3	(Terminal module)	030		Single	<b>√</b> :G0			
5 6 7 8				Dual 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	X:RESET A latched output relay (section 12.2.4 M)			
	(The setpoint is assigned to the Command Module for use in a specific program).							

#### CONTROL & DISPLAY PRODUCT

PART 1 12. SETUP ZONE 12.2.5 0



# TEXT

Duty Text can be entered to denote the Input duty, the location or the tag reference of the input device.

Up to 12 digits of text can be entered into the display and there is a menu of Letters, Numbers and Symbols to choose from.



Step *E/W* to TRAVERSE the characters.



Scroll **N/S** to SET the characters.



Step *E* to CONFIRM.



A default message will appear if no user text is entered.





# STATUS

As a result of plant maintenance, it may be necessary to temporarily disable a particular channel card location.

The location can be properly EXCLUDED to prevent false alarm states occurring.



Scroll N/S to SELECT.



Step E to CONFIRM.





Reinstate INCLUDE after the interruption is over.



- Always EXCLUDE a channel card location when changing a channel card otherwise the Command module will perceive a FAULT.
  - Remember that where a channel card that has been first EXCLUDED and replaced, the new card will need to be SETUP, INCLUDED and REFRESHED (section 12.2.3 )





#### MINMAX

The maximum value and minimum value that the output signal has reached since the last RESET is stored.

Stored values of previous MIN and MAX can be RESET to the current value.





Scroll N/S for YES/NO.



Step E to CONFIRM.





Data will also be recorded in the Log (section 12.1.5 and section 9).



PART 1
13. SPECIAL
CONTROL AND
MONITORING
FUNCTIONS

13 special control and monitoring functions



#### CONTROL & DISPLAY PRODUCT

PART 1
13. SPECIAL
CONTROL AND
MONITORING
FUNCTIONS

The standard Command module is equipped with a processor program that provides the alarm configuration routines described in section 12, enabling elementary monitoring and shutdown functions to be programmed by the user directly through the keypad.



 Special function routines or system upgrades can also be installed into the Command module for control programs & function blocks of greater complexity.
 The program is installed through the LAN 1 data connecting terminals or the LAN 2 data plug-in connector (section 2.1).













The complete Commander setup can also be installed into the Command module through the LAN 1 or LAN 2 data ports, using a standard PC programming tool (section 2).

The standard communication protocol is MODBUS and it is provided with the system in CD format. An RS485/RS232 connector will be required for the PC data port.

Please contact our technical sales department for details.

TX2199: Commander Configuration Software Package.





PART 1
14. ADDING AN
OPERATOR
INTERFACE OR PC

14 adding an operator interface or PC

**4** of 169

CONTROL & DISPLAY PRODUCT

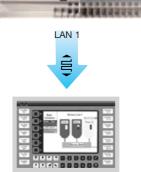
PART 1
14. ADDING AN
OPERATOR
INTERFACE OR PC

The standard Command module will display all program and dynamic operating information on its integral graphic LCD readout. (section 12).



 This same data can be transferred via Modbus to an operator interface panel or PC to provide a larger and more comprehensive information display.

The LAN 1 or the LAN 2 datacomms ports can be used for this purpose. (section 2).



SCADA software can be loaded into the operator interface to produce a comprehensive plant graphic display tailored to individual requirements.
 Configuration software in WINDOWS format is available from TROLEX for this purpose.







#### SYSTEM DESIGN

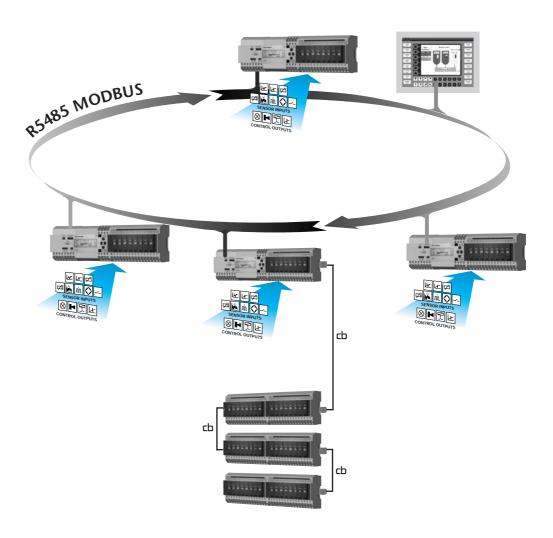
Commander Systems can be supplied with an installed processor program and SCADA graphic package to specific design requirements, complete with an Operator Interface panel.





PART 2
15. DISTRIBUTED
COMMANDER
SYSTEMS

# distributed commander systems





PART 2
15. DISTRIBUTED
COMMANDER
SYSTEMS

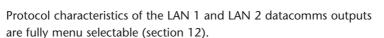
Distributed individual commander systems can be combined on a data network to communicate data to a *master* PC or central control room.

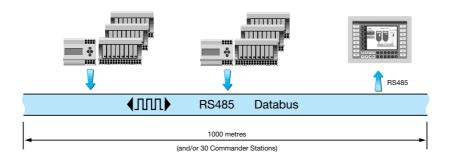
#### 15.1 DATA COMMUNICATIONS

All functional data accumulated by the Command module is available from both the LAN 1 and LAN 2 output ports of the command module in the form of multidrop RS485 datacomms (section 2). This will support MODBUS protocol and up to 30 Commander stations can be combined on the databus over a total distance of about 1000 metres.

In practice the communications capability is influenced by the

In practice the communications capability is influenced by the type of cable used and the system architecture - our Commander system applications engineers can provide technical assessment of individual installation designs.









PART 2
16. DATACOMMS
REPEATER
MODULE

P5506 datacomms
repeater module
(Ex Group I)

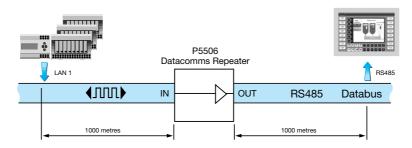




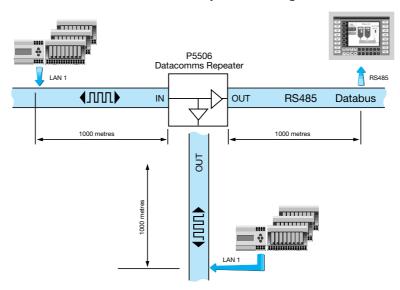
PART 2
16. DATACOMMS
REPEATER
MODULE

# P5506 DATACOMMS REPEATER MODULE

A P5506 Datacomms repeater module can be added into a databus in point-to-point format, where increased operating distance is required on LAN 1 or LAN 2 networks. Each additional module will extend the distance by about 1000 metres dependent upon the installation parameters. The device is certified Ex Intrinsically Safe for use in Group I hazardous areas.



The P5506 Datacomms repeater also incorporates an additional output repeater so enabling convenient branches can be added to a distributed system at strategic locations.





In practice, the structural architecture and operating distribution of a Commander system are both influenced by related technical parameters:

- The topology and distribution of the plant
- The type of sensors and plant devices
- The area classification of a system and hazardous area limitations.
- System power requirements and power distribution.
- The type of cable used for the databus.
- The overall resultant time response of the system

Our Commander system application engineers can provide technical assessment of individual installation designs.

PART 2
16. DATACOMMS
REPEATER
MODULE

### 16.2 SETTING UP A P5506 DATACOMMS REPEATER MODULE

A selector switch is provided on the front panel of the module for setting up the baud rate and function status.



### • BAUD RATE

The baud rate can be optimised to individual system parameters Range: 2.4k up to 115k

1	2	3	4	
_	_	_		2.4k baud
_	_	_		4.8k baud
_	_	_		9.6k baud
_	_	_		14.4k baud
_	_	_		19.2k baud
_	_	_		38.4k baud
_	_	_		57.6k baud
-	-	-		115.2k baud

### • MASTER/SLAVE

Set to the SLAVE position for all standard applications. (The MASTER position is used on system configurations to define the base station).

	_	Slave
	_	Maste

### 16.3 FIBRE OPTIC DATACOMMS

The P5506 Datacomms Repeater Module is also available with optical fibre data communications.

Please contact our Commander Design Department for details and assistance.







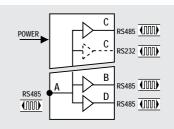
PART 2
16. DATACOMMS
REPEATER
MODULE

### P5506 DATACOMMS REPEATER MODULE

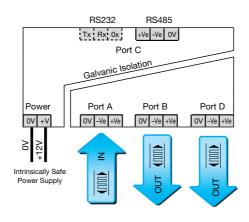
- RS485 Datacomms repeater with galvanic isolation.
- Dual data output for branching networks.
- Increase distance on Commander station LAN 1 and LAN 2 networks.
- Baud rate selectable.
- Certified Ex Intrinsically Safe for use in Group I Hazardous Areas.
- Optional Fibre Optic Datacomms.
- Optional RS232 PC interface.

### **GROUP I**

### RS485 isolated datacomms

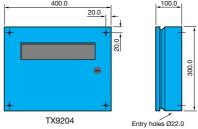


#### Connections:



• The screen of the data cables MUST be connected to a secure instrument earth at ONE point only.

Power Supply:	12V dc from an approved power supply.	
Current Consumption:	60mA	
Physical Layer:	RS485 Hard wired. (Also available with fibre optic couplers to specification).  (Dataport C can be configured for RS232 format to specification).	
Protocol:	Non-specific.	
Maximum Cable Distance:	1000m per output (Dependent upon baud rate and cable parameters).	
Maximum Comms Points:	30 per output.	
Speed:	Selectable up to 115k baud max.	
Recommended Cable:	Twisted pair • 0.5mm <sup>2</sup> • Overall screen	
Dimensions:	+ 400.0    +100.0	



All dimensions in mm.

Order Reference: P 5 5 0 6 DATACOMMS REPEATER MODULE. GROUP I

Please specify:

- Hardwire Datacomms
  - (.21) s (.22)

(.31)

(.32)

- Fibre Optic DatacommsRS485 Dataport C
- RS232 Dataport C

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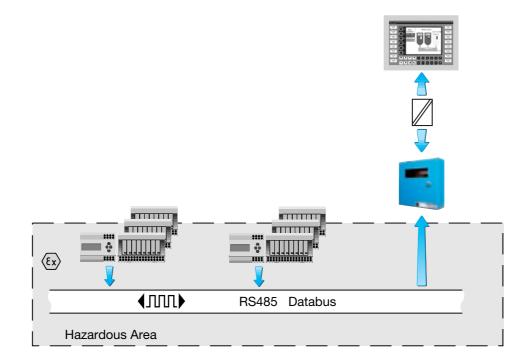
PART 2 16. DATACOMMS REPEATER **MODULE** 



### $\langle \epsilon_{ m x} angle$ 16.4 USING THE P5506 DATACOMMS REPEATER MODULE AS PART OF A HAZARDOUS AREA INTERFACE.

A safety barrier may be required where a databus from a Commander network is interfacing with non-approved equipment such as a PC.

The P5506 Datacomms Repeater Module can be configured as an RS485/RS232 PC interface with locally sourced power isolated from the main databus.



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# assembling systems

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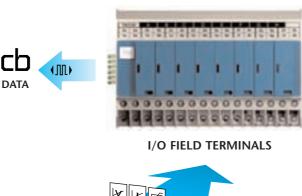
PART 3
ASSEMBLING
SYSTEMS

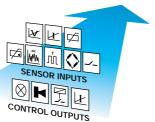
#### COMMANDER APPLICATION SIMPLICITY

In order to exploit the unique benefits of the Commander philosophy, it is necessary to think about a Control and Monitoring system in a completely different way.

Traditionally field devices, out on a plant or process, are cabled back to a rail of terminal blocks at the control centre. Individual wires continue the transfer of the data acquired, back to a central data interface or display usually routed in large and complex wiring harnesses.

Commander Terminal modules are rail mounted in the same way as conventional terminals. They have heavy duty screw-clamp terminals, each capable of accepting two large conductors side by side. Their performance and size are similar to that of normal heavy duty rail mounted terminals – Commander Terminal modules ARE the plant cable terminations, with the advantage that they are also 'smart' or data intelligent.





All plant I/O data is transmitted from the Commander Terminal Modules to the central interface by a single Commandbus data cable so eliminating practically all the panel wiring as well as dramatically reducing manufacturing costs. Reliability is improved and fault diagnosis is considerably simplified.

PLAN YOUR COMMANDER SYSTEM LAYOUT WITH THIS IN MIND.



• Conventional Panel Wiring

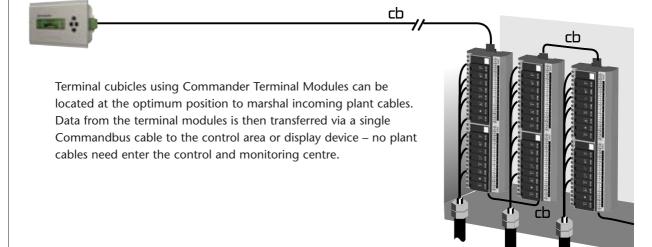


• Complex Cable Looms



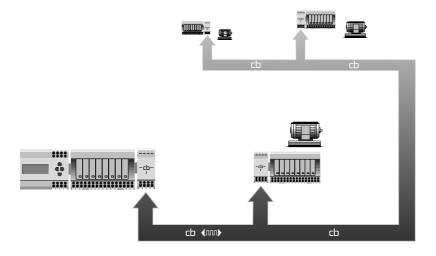
PART 3
ASSEMBLING
SYSTEMS





FIELD I/O

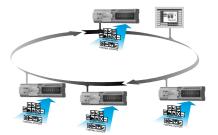
This principle can be maximised even further – the Commandbus can extend out into the plant and connect to a Terminal Module dispersed at a convenient location, collecting I/O data from groups of sensors or commanding control devices. Complex and expensive cable runs can be eliminated.



PART 3
ASSEMBLING
SYSTEMS

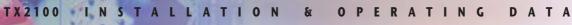
### **COMMANDER DESIGN VERSATILITY**

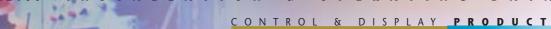
Whether the installation is a few sensors and control devices monitoring a small machine or a major distributed process monitoring project, the same Commander system can deal with it. Furthermore, a Commander system design does not need to be 'committed' at an early stage in the project. Once the Commander back-bone is in place, the format can be adapted or changed to suit the design requirements of the plant as it develops. System configuration can be modified as required, sensor and control device functions can be individually programmed and control/alarm functions can be decided during final commissioning. The same versatility can be exploited for later plant upgrades and changes.



Install a standard software package or a PLC database into the Command Module and highly complex control and monitoring functions can be executed.









TROLEX



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PART 3
17. SYSTEM
PLANNING

### 17 SYSTEM PLANNING

### **ICON LIBRARY**

Drawings of the various modules in the Commander range can be provided for use on a PC in JPEG format. This simplifies the design and planning of an overall Commander System and ensures consistency of layout.



#### **SETUP DATA**

It is vitally important that all SETUP data for the Command module and the Channel Cards are correctly recorded. A series of 6 SETUP data forms is provided in the following section so that programming information can be logged.

This can be done prior to the installation and commissioning of the system as an implementation instruction to the installation engineer, or it may be used to post-record the data that is entered during the installation process.

### **COMMANDER SYSTEM CONFIGURATION FROM A PC**

### **DIRECT CONFIGURATION**

The complete Commander setup can also be installed into the Command module through the LAN 1 or LAN 2 data ports, using a standard PC programming tool (section 2).

The standard communication protocol is MODBUS and is provided in CD format with each system. An RS485/RS232 connector will be required for the PC data port.



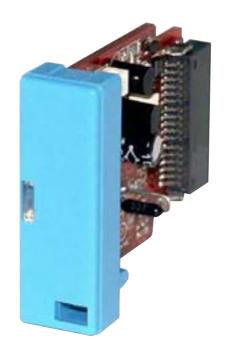


PART 3 17. SYSTEM PLANNING



PART 3
18. WHICH
CHANNEL CARD?

# 18 which channel card?





PART 3
18. WHICH CHANNEL CARD?

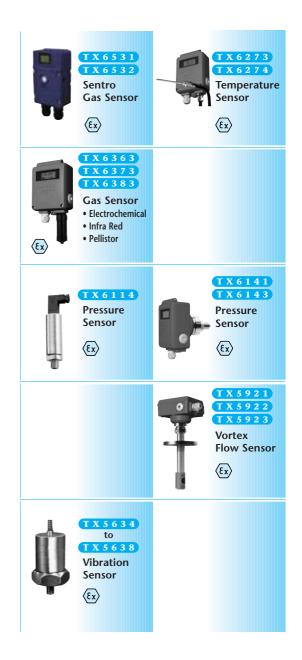
## I ANALOGUE INPUT CHANNEL CARDS

4...20mA INPUT



TX2141.301 TX2141.302

- Current regulated 4...20 process signals.
- 2, 3 and 4 wire connections.
- Loop powered sensors.
- Sensors, signal loops, process instruments.





PART 3
18. WHICH
CHANNEL CARD?

## I ANALOGUE INPUT CHANNEL CARDS

0.4...2V SIGNALS



TX2141.303 TX2141.304

- Sensors and monitoring devices with analogue voltage outputs.
- Voltage signal generators.





PART 3 **18. WHICH CHANNEL CARD?** 

# ANALOGUE INPUT CHANNEL CARDS

PT100 SIGNALS 卢

TX2141.306 TX2141.307



TX2141.308

- Standardised to DIN43760.
- -50°C to 400°C ranges.
- Linearised response.
- Line compensation.





**Temperature** Sensor

• PT100 element

- SEMICONDUCTOR SIGNALS
- 应

- Linearised input.
- -50°C to 300°C ranges.
- **E**conomical.



### T X 2 0 7 0

**Temperature** Sensor

- KTY21 & KTY84
- Semiconductor element

#### ac VOLTAGE SIGNALS



TX2141.309

- ac RMS detection.
- Vibration sensors.
- Load cells.
- ac generators.
- ac measuring instruments.
- 10Hz to 20KHz ranges.



T X 5 6 3 1 T X 5 6 3 3

Vibration Sensor

### mV SIGNALS



TX2141.310

- Strain gauges.
- Load cells.
- Bridge sensing circuits.
- Pressure sensors.
- Measuring devices.
- 1mV/V to 100mV/V ranges.



TX6251

Infra Red **Temperature Sensor** 





T X 6 3 8 4

**Remote Flammable Gas Sensor** 





### PULSE FREQUENCY INPUT CHANNEL CARDS

### **PULSE FREQUENCY INPUT**



TX2141.401

- Pulse or frequency signals.
- Switches, proximity sensors, pulse wheels, frequency generators, photocells.
- Frequency measurement, speed sensing, slip monitoring, differential frequency, pulse comparison, frequency generators.
- Sensors with frequency outputs
   5...15Hz, 0...10kHz etc.
- Pulse generating flow sensing devices and turbines.
- Motor and conveyor monitoring.











PART 3
18. WHICH CHANNEL CARD?

## I ONOFF/STATE INPUT CHANNEL CARDS

#### **ONOFF/STATE INPUT**



TX2141.501



TX2141.502



TX2141.503



TX2141.504

- Simple ONOFF switches; pressure switches, reed switches, limit switches, thermostats.
- NAMUR proximity sensors, position sensing, interlocking.
- Fail safe switch line monitoring.
- Current state change for fire and gas applications. Smoke, flame, break glass, etc.





## TX2100 INSTALLATION & OPERATING DATA

CONTROL & DISPLAY PRODUCT

PART 3 18. WHICH CHANNEL CARD?



### ONOFF/STATE OUTPUT CHANNEL CARDS

ONOFF/STATE OUTPUT	Solid state output switch.	
了 <sub>人</sub>	<ul> <li>Relay driver, small lamp driver, logic driver.</li> </ul>	
TX2141.603	Economical output switching.	
	Quad output – high density.	
ONOFF/STATE OUTPUT	Voltage free contact.	
TX2141.604	<ul> <li>Isolated switching power for relays, contactors and alarm devices.</li> </ul>	



# TX2100 INSTALLATION & OPERATING DATA

CONTROL & DISPLAY PRODUCT





### ■ ANALOGUE OUTPUT CHANNEL CARDS

ANALOGUE OUTPUT



TX2141.701

- Motorised valves, servo controllers, process loops, regulators, positioning devices
- Signal repeaters





PART 3
19. CONFORMITY
CHECK



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### & DISPLAY PRODUCT

### PART 3 19. CONFORMITY

Classification for Commander Modules	(Ex) GROUP I
<ul> <li>Ensure the correct Supply Voltage system.</li> </ul>	12V dc from an APPROVED POWER SUPPLY (TX6641 and TX6642)
<ul><li>Ensure the correct</li><li>Sensors and Plant Devices</li></ul>	12V dc compatible and APPROVED (check compliance with installation and cabling requirements).

- Ensure correct Datacomms compatibility for LAN1 and LAN2 and associated equipment.
- Do the channel card types concur with the plant devices being used.
- Secure Commandbus cables. Fit DIN RAIL end clamps.
- Commander Modules MUST be mounted into approved metal housings.
- Check that all terminals are properly tightened.
- Segregate power and signal cabling.
- **—** Carry out a power audit of each Terminal Module (section 3.8).
- Check that the total power consumption is within the power rating of the power supply being used and the limits individually specified for Hazardous Area Commander Systems.

Command Module (section 2)		mA
Terminal Modules (section 3.9)		mA
Commandbus Repeater Modules (section 5.6)		mA
	TOTAL:	mA



If more than one Power Supply is used on a Commander system ensure that interlinking power conductors have been omitted from the commandbus (section 5.4).

- Check that the cable lengths do not exceed permissible restrictions and that the characteristics of the cable are within the limits specified for hazardous area operation.
- Check that the cable glands comply with hazardous area requirements and that the cables are correctly terminated.
- Group I Hazardous Area Commander Systems may need a power supply main isolator in order to comply with local regulations.



Have your system assessed by our Commander Engineering experts.



PART 3
20. APPROVALS
AND
CERTIFICATION

20 approvals and certification

**7** of 174

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PART 3
20. APPROVALS
AND
CERTIFICATION

### **Intrinsically Safe**



The Commander system is certified Intrinsically Safe Group I apparatus for use in potentially explosive atmospheres to EURONORM standards when used with an approved power supply or safety barrier.

Group I: EEx ia I I M1

**ATEX** 

The system is designed to comply with the ATEX directive (94/9/EEC).

# (6

### **Electro Magnetic Compatibility**

The system is designed to comply with the EC directive on EMC (89/336/EEC).

PROTECTING
THE
ENVIRONMENT

Many of our products are often used to monitor the quality of environmental conditions consequently Trolex is also particularly aware of the need to protect human health and the environment in which we live.

The Company has instituted a radical environment protection policy to ensure that all aspects of our manufacturing programme have the minimum possible detrimental impact on the environment. This covers all stages beginning with sustainable product design supported by careful selection of the materials used in their production, through to managed recovery and disposal at the end of the useful life of a product.

This policy also incorporates the principles of the Waste Electrical and Electronics Equipment (WEEE) directive, and the associated Restriction of Hazardous Substances (RoHS) directive, to be implemented in EU countries.

Progress is already well advanced on the introduction of a completely new range of products that maximise the central principle of sustainable design with the intention of reducing the end-of-life cost to the end user.

All Trolex products are manufactured to exacting standards in accordance with our stringent quality control ethos. Having chosen to use one of our products will, in itself, guarantee extended durability and a long operating life, endorsed by our commitment to recycling and recovery.

- \*\*\* All packaging materials are carefully selected to be bio-degradable or re-cycleable where possible.
- \*\*\* All plastic materials are identified for recycling purposes and re-cycled materials are used where it is possible to do so.
- \*\* Printing paper and material are sourced from suppliers that have a declared environmental management system.
- Product design centred around high quality and long term durability. Modular architecture both in construction and software design suitable for future upgrades and adaptability to alternative duty.
- Ease of product disassembly, minimisation of fixing devices, and clear separation of functional parts to benefit reuse and re-cycling.
- \*\*\* Control and monitoring of suppliers of components and sub-assemblies. Deal only with suppliers that have a defined commitment to environmental monitoring principles.
- \*\*\* Control the use of restricted substances within the design process. Deal only with suppliers that have a defined commitment to the control of restricted substances.
- Provide an efficient high speed service within Trolex for repair, refurbishing and conversion of products for alternative duty.
- Provision of an end-of-life product Take-back service for recovery, re-use, and recycling of electrical and electronic components. Retain the packaging of a new product and re-use it to return the device to us at the end of its working life. Trolex will guarantee to recover all materials and components, where practicable and arrange for them to be re-cycled in an appropriate and in a safe manner.

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